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BOUNDING THE OPTIMAL RATE OF THE ICSI AND ICCSI PROBLEM

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Abstract. In this work we study both the index coding with side information (ICSI) problem introduced by Birk and Kol in 1998 and the more general problem of index coding with coded side information (ICCSI), described by Shum *et al* in 2012. We estimate the optimal rate of an instance of the index coding problem. In the ICSI problem case, we characterize those digraphs having min-rank one less than their order and we give an upper bound on the min-rank of a hypergraph whose incidence matrix can be associated with that of a 2-design. Security aspects are discussed in the particular case when the design is a projective plane. For the coded side information case, we extend the graph theoretic upper bounds given by Shanmugam *et al* in 2014 on the optimal rate of index code.

Key words. Index coding, network coding, coded side information, broadcast with side information, min-rank.

AMS subject classifications. 05C50, 68P30, 94A05

1. Introduction. Since its introduction in [6], the problem of index coding has been generalized in a number of directions [1, 3, 8, 13, 14, 16]. It is a problem that has aroused much interest in recent years; from the theoretical perspective, its equivalence to network coding has established it as an important area of network information theory [18, 17]. In the classical case, a central broadcaster has a data file $x \in \mathbb{F}_q^n$. There are n users each of whom already possesses some subset of components of x as its side-information and each of whom requests some component x_i of the file. The index coding problem is to determine the minimum number of transmissions required so that the demands of all users can be met, given that data may be encoded prior to broadcast. This problem can be associated with a directed graph, or a hypergraph if the case is extended to consider a scenario of $m > n$ users. Several authors have given various bounds on the length of an index code, which refers to the number of transmissions used to meet clients' demands for a given instance of the problem. It is well known that for the case of linear index coding, the min-rank of the associated side-information graph is the minimal number of broadcasts required. In [24], the authors give several graph theoretic upper bounds based on linear programming. In [16] the authors describe the scenario of linear index coding with coded side information. In this model, users may request a linear combination of the data held by the sender and are assumed to each have some set of linear combinations of the data packets. One motivation for this more general model is that it may serve a larger number of applications than the case for uncoded side-information, such as broadcast relay networks and wireless distributed storage systems. The set-up in [16] does not have an obvious representation in the form of a side-information hypergraph. However, as we show here, practically all the results of [24] can be extended to this case.

In this paper we present new bounds on the optimal rate for different instances of the index coding problem. For the case of uncoded side information the problem will be referred to as an index coding with side information (ICSI) problem. For the case

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of encoded side information we will describe this as an ICCSI instance. In the first part we give bounds on the minimum number of transmissions required for particular instances of the ICSI problem where the corresponding side-information hypergraph can be associated with the incidence matrix of a design. This comprises Sections II-V. The remainder of the paper is concerned with upper bounds on the total transmission time for the ICCSI problem and extends the results of [24] for this more general case. In Section II we give relevant definitions and results on incidence structures such as designs. In Section III the ICSI problem is described. In Section IV, extending results of [15], we characterize those digraphs having min-rank one less than their order. In Section V we give an upper bound on the min-rank of a hypergraph whose incidence matrix can be associated with that of a 2-design and discuss a security aspect for such special instances of the ICSI problem. In Section VI we describe the ICCSI problem before finally giving several upper bounds on the transmission time of an ICCSI instance based on linear programming.

2. Preliminaries. We establish some notation to be used throughout the paper. We will assume that q is a power of a prime p , say $q = p^\ell$. For any positive integer n , we let $[n] := \{1, \dots, n\}$. We write \mathbb{F}_q to denote the finite field of order q and use $\mathbb{F}_q^{n \times t}$ to denote the vector space of all $n \times t$ matrices over \mathbb{F}_q .

Given a matrix $X \in \mathbb{F}_q^{n \times t}$ we write X_i and X^j to denote the i th row and j th column of X , respectively. More generally, for subsets $\mathcal{S} \subset [n]$ and $\mathcal{T} \subset [t]$ we write $X_{\mathcal{S}}$ and $X^{\mathcal{T}}$ to denote the $|\mathcal{S}| \times t$ and $n \times |\mathcal{T}|$ submatrices of X comprised of the rows of X indexed by \mathcal{S} and the columns of X indexed by \mathcal{T} respectively. We write $\langle X \rangle$ to denote the row space of X .

A finite *incidence structure* $\mathcal{S} = (\mathcal{P}, \mathcal{B}, \mathcal{I})$, consists of a pair of finite sets \mathcal{P} (its points) and \mathcal{B} (its blocks), and an incidence relation $\mathcal{I} \subset \mathcal{P} \times \mathcal{B}$. We say that p is contained in or is incident with B if $(p, B) \in \mathcal{I}$.

DEFINITION 1. Let t, v, k and λ be positive integers. An incidence structure $\mathcal{D} = (\mathcal{P}, \mathcal{B}, \mathcal{I})$ is called a t -(v, k, λ) block design if

- (1) $|\mathcal{P}| = v$;
- (2) $|B| = k$ for all $B \in \mathcal{B}$;
- (3) every t -set of points of \mathcal{P} are contained in precisely λ blocks of \mathcal{B} .

Often a t -(v, k, λ) block design is simply referred to as a t -design. Designs are well-studied objects in combinatorics with many applications. The interested reader is referred to [28, 11, 10] for further information, but we present sufficient detail here to meet our purposes. The number of blocks b of a t -(v, k, λ) design is $b = \lambda \binom{v}{t} / \binom{k}{t}$ and the number of blocks containing any given point of \mathcal{P} is $r = \lambda \binom{v-1}{t-1} / \binom{k-1}{t-1}$, which is its *replication number*. In the case of a 2-design we have $r = \lambda(v-1)/(k-1)$. An important parameter of a t -design is its *order*, defined to be $n = r - \lambda$.

DEFINITION 2. Let $\mathcal{S} = (\mathcal{P}, \mathcal{B}, \mathcal{I})$ be an incidence structure with $|\mathcal{P}| = v$ and $|\mathcal{B}| = b$. Let the points be labelled $\{p_1, \dots, p_v\}$ and the blocks be labelled $\{B_1, \dots, B_b\}$. An incidence matrix for \mathcal{S} is a $b \times v$ matrix $A = (a_{i,j})$ with entries in $\{0, 1\}$ such that

$$a_{i,j} = \begin{cases} 1 & \text{if } (p_j, B_i) \in \mathcal{I} \\ 0 & \text{if } (p_j, B_i) \notin \mathcal{I} \end{cases}$$

The code of \mathcal{S} over \mathbb{F}_q is the subspace $C_q(\mathcal{S})$ of $\mathbb{F}_q^{|\mathcal{P}|}$ spanned by the rows of A .

DEFINITION 3. Let \mathcal{S} be an incidence structure and let q be a prime power, the

q -rank of \mathcal{S} is the dimension of the code $C_q(\mathcal{S})$ and is written

$$\text{rank}_q(\mathcal{S}) = \dim(C_q(\mathcal{S})).$$

The following result was proved by Klemm [19]. We will see in Section V that this gives an immediate upper bound on the min-rank of a class of instances of the index coding problem.

THEOREM 4. *Let $\mathcal{D} = (\mathcal{P}, \mathcal{B})$ be a 2 - (v, k, λ) design of order n and let p be a prime dividing n . Then*

$$\text{rank}_p(\mathcal{D}) \leq \frac{|\mathcal{B}| + 1}{2}.$$

Moreover, if p does not divide λ and p^2 does not divide n , then

$$C_p(\mathcal{D})^\perp \subseteq C_p(\mathcal{D})$$

and $\text{rank}_p(\mathcal{D}) \geq v/2$.

A 2 - $(n^2 + n + 1, n + 1, 1)$ design, for $n \geq 2$, is called a *projective plane* of order n . A projective plane of order n is an example of a *symmetric design*, that is, it has the same number of points as blocks, so $|\mathcal{P}| = |\mathcal{B}|$.

The following can be read in [2, Theorem 6.3.1].

THEOREM 5. *Let Π be a projective plane of order n and p be a prime such that $p|n$. Then the p -ary code of Π , $C_p(\Pi)$, has minimum distance $n + 1$. Moreover the codewords of minimal weight in $C_p(\Pi)$ are the scalar multiples of the rows of the incidence matrix of Π .*

Chouinard, in [9], proved that:

THEOREM 6. *Let $C_p(\Pi)$ be a code arising from a projective plane of prime order p . Then no codeword has weight in the interval $[p + 2, 2p - 1]$.*

DEFINITION 7. *A digraph is a pair $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ where:*

- \mathcal{V} is the set of vertices of \mathcal{G} ,
- $\mathcal{E} \subset \mathcal{V} \times \mathcal{V}$ is the set of arcs (or directed edges) of \mathcal{G} .

An arc of \mathcal{G} is an ordered pair $e = (u, v) \in \mathcal{E}(\mathcal{G})$ for some $u, v \in \mathcal{V}$. In the case that $u \neq v$, the vertex u is called the tail of e and v the head of e . The arc e is called an out-going arc of u and an in-coming arc of v . The out-degree of a vertex u , $\text{deg}_O(u)$ is the number of out-going arcs, and the in-degree of a vertex u , $\text{deg}_I(u)$ is the number of in-coming arcs. \mathcal{G} is called an undirected graph, or a graph, if $(u, v) \in \mathcal{E}$ whenever $(v, u) \in \mathcal{E}$. If \mathcal{G} is a graph then each pair of arcs (u, v) and (v, u) are represented by the unordered pair $\{u, v\}$, which is called an edge. The number of vertices of a digraph is called its order.

We assume that all digraphs have finite order.

DEFINITION 8. *A path in a graph \mathcal{G} (respectively in a digraph), is a sequence of distinct vertices (u_1, u_2, \dots, u_k) , such that $\{u_i, u_{i+1}\} \in \mathcal{E}$ ($(u_i, u_{i+1}) \in \mathcal{E}$, respectively) for all $i \in [k - 1]$. If a path is closed, i.e. $\{u_k, u_1\} \in \mathcal{E}$ ($(u_k, u_1) \in \mathcal{E}$, respectively), then it is called circuit. A digraph that is not a graph is called acyclic if it contains no circuits. A graph is acyclic if it has no circuits with at least 3 vertices.*

Let $\nu(\mathcal{G})$ be the *circuit packing number* of \mathcal{G} , namely, the maximum number of vertex-disjoint circuits in \mathcal{G} . A *feedback vertex set* of \mathcal{G} is a set of vertices whose removal destroys all circuits in \mathcal{G} . Let $\tau(\mathcal{G})$ denote the *minimum size of a feedback*

vertex set of \mathcal{G} . We denote by $\alpha(\mathcal{G})$ the maximum size of vertex subset such that induced subgraph in \mathcal{G} is acyclic. Since such a subset of vertices is the complement of a feedback vertex set, we have $\alpha(\mathcal{G}) = |\mathcal{G}| - \tau(\mathcal{G})$. In the case that \mathcal{G} is a graph, $\alpha(\mathcal{G})$ is the maximum size of an independent (pairwise non-adjacent) set of vertices,

DEFINITION 9. A clique of a digraph is a set of vertices that induces a complete subgraph of that digraph. A clique cover of a digraph is a set of cliques that partition its vertex set. A minimum clique cover of a digraph is a clique cover having minimum number of cliques. The number of cliques in such a minimum clique cover of a digraph is called the clique cover number of that digraph. We denote by $\text{cc}(\mathcal{G})$ the clique cover number of a digraph \mathcal{G} .

DEFINITION 10. Let $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ be a digraph of order n . A matrix $M = (m_{i,j}) \in \mathbb{F}_q^{n \times n}$ is said to fit \mathcal{G} if

$$m_{i,j} = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } (i, j) \notin \mathcal{E} \end{cases}$$

The min-rank of \mathcal{G} over \mathbb{F}_q is defined to be

$$\text{minrk}_q(\mathcal{G}) = \min\{\text{rank}_q(M) : M \text{ fits } \mathcal{G}\}$$

We also have analogous definitions for a graph.

DEFINITION 11. A (directed) hypergraph \mathcal{H} is a pair $(\mathcal{V}, \mathcal{E})$, where \mathcal{V} is a set of vertices and \mathcal{E} is a set of hyperarcs. A hyperarc e itself is an ordered pair (v, H) , where $v \in \mathcal{V}$ and $H \subseteq \mathcal{V}$, they respectively represent the tail and the head of the hyperarc e .

DEFINITION 12. Let $|\mathcal{V}| = n$ and $|\mathcal{E}| = m$. Let the hyperarcs be labelled $\{e_1, \dots, e_m\}$, a matrix $M = (m_{i,j}) \in \mathbb{F}_q^{m \times n}$ fits the hypergraph if

$$m_{i,j} = \begin{cases} 1 & \text{if } j \text{ is the tail of } e_i \\ 0 & \text{if } j \text{ does not lie in the head of } e_i \end{cases}$$

The min-rank of \mathcal{H} over \mathbb{F}_q is defined to be

$$\text{minrk}_q(\mathcal{H}) = \min\{\text{rank}_q(M) : M \text{ fits } \mathcal{H}\}$$

3. Index coding with side information. The Index Coding with Side Information (ICSI) problem is described as follows. There is a unique sender S , who has a data matrix $X \in \mathbb{F}_q^{n \times t}$. There are also m receivers, each with a request for a data packet X_i , and it is assumed that each receiver has some side-information, that is, a client i has a subset of messages $X_{\mathcal{X}_i}$, where $\mathcal{X}_i \subseteq [n]$ for each $i \in [m]$. The packet requested by i is denoted by $X_{f(i)}$, where $f : [m] \rightarrow [n]$ is a (surjective) demand function. Here we assume that $f(i) \notin \mathcal{X}_i$ for all $i \in [m]$. We may assume that each i th receiver requests only the message $X_{f(i)}$, since a receiver requesting more than one message can be split into multiple receivers, each of whom requests only one message and has the same side information set as the original [1].

For the remainder, let us fix t, m, n to denote those parameters as described above. Then for any $\mathcal{X} = (\mathcal{X}_1, \dots, \mathcal{X}_m)$, $\mathcal{X}_i \subseteq [n]$ and map $f : [m] \rightarrow [n]$, the corresponding instance of the ICSI problem (or the ICSI instance) is denoted by $\mathcal{I} = (\mathcal{X}, f)$. It can also be conveniently described by a side-information (directed) hypergraph [1].

DEFINITION 13. Let $\mathcal{I} = (\mathcal{X}, f)$ be an ICSI instance. The corresponding side information hypergraph $\mathcal{H} = \mathcal{H}(\mathcal{X}, f)$ has vertex set $\mathcal{V} = [n]$ and hyperarc set \mathcal{E} , defined by

$$\mathcal{E} = \{(f(i), \mathcal{X}_i) : i \in [m]\}.$$

REMARK 14. If we have $m = n$ and $f(i) = i$ for all $i \in [n]$, the corresponding side information hypergraph has precisely n hyperarcs, each with a different origin vertex. It is simpler to describe such an ICSI instance as a digraph $\mathcal{G} = ([n], \mathcal{E})$, the so-called side information digraph [3]. For each hyperarc (i, \mathcal{X}_i) of \mathcal{H} , there are $|\mathcal{X}_i|$ arcs (i, j) of \mathcal{G} , for $j \in \mathcal{X}_i$. Equivalently, $\mathcal{E} = \{(i, j) : i, j \in [n], j \in \mathcal{X}_i\}$.

DEFINITION 15. Let N be a positive integer. We say that the map

$$E : \mathbb{F}_q^{n \times t} \rightarrow \mathbb{F}_q^N,$$

is an \mathbb{F}_q -code of length N for the instance $\mathcal{I} = (\mathcal{X}, f)$ if for each $i \in [m]$ there exists a decoding map

$$D_i : \mathbb{F}_q^N \times \mathbb{F}_q^{|\mathcal{X}_i|} \rightarrow \mathbb{F}_q^t,$$

satisfying

$$\forall X \in \mathbb{F}_q^{n \times t} : D_i(E(X), X_{\mathcal{X}_i}) = X_{f(i)},$$

in which case we say that E is an \mathcal{I} -IC. E is called an \mathbb{F}_q -linear \mathcal{I} -IC if $E(X) = LX$ for some $L \in \mathbb{F}_q^{N \times n}$, in which case we say that L represents the code E . If $t = 1$, E is called scalar linear.

The following well-known results quantify the minimal length of a linear index code in respect of its side-information hypergraph (cf. [13])

LEMMA 16. An $\mathcal{I}(\mathcal{X}, f)$ -IC of length N over \mathbb{F}_q has a linear encoding map if and only if there exists a matrix $L \in \mathbb{F}_q^{N \times n}$ such that for each $i \in [m]$, there exists a vector $\mathbf{u}^{(i)} \in \mathbb{F}_q^n$ satisfying

- (1) $\text{Supp}(\mathbf{u}^{(i)}) \subseteq \mathcal{X}_i$
- (2) $\mathbf{u}^{(i)} + \mathbf{e}_{f(i)} \in \langle L \rangle.$

THEOREM 17. Let $\mathcal{I} = (\mathcal{X}, f)$ be an instance of the ICSI problem, and \mathcal{H} its hypergraph. Then the optimal length of a q -ary linear \mathcal{I} -IC is $\text{minrk}_q(\mathcal{H})$.

Achievable schemes based on graph-theoretic models for constructing index codes (i.e. upper bounds for index coding) were largely studied [1, 3, 8, 24].

One of these methods comes from the well-known fact that all the users forming a clique in the side information digraph can be simultaneously satisfied by transmitting the sum of their packets [6]. This idea shows that the number of cliques required to cover all the vertices of the graph (the clique cover number) is an achievable upper bound.

A lower bound on the min-rank of a digraph was given in [3]. An acyclic digraph has min-rank equal to its order (see for instance [3]) and for any subgraph \mathcal{G}' of a graph \mathcal{G} we have

$$\text{minrk}_q(\mathcal{G}') \leq \text{minrk}_q(\mathcal{G}).$$

Let M be a matrix that fits \mathcal{G} , the sub-matrix M' of M restricted on the rows and columns indexed by the vertices in $\mathcal{V}(\mathcal{G}')$ is a matrix that fits \mathcal{G}' . These two results are summarized in the following theorem.

THEOREM 18. *Let \mathcal{G} be a digraph. Then*

$$\alpha(\mathcal{G}) \leq \text{minrk}_q(\mathcal{G}) \leq \mathbf{cc}(\mathcal{G}).$$

Instead of covering with cliques, one can cover the vertices with circuits. In [8] the *circuit-packing bound* was implicitly introduced by the authors. Indeed, Chaudhry and Sprintson construct a linear index code partitioning the graph of the ICSI instance in disjoint circuits. The same bound was explicitly given in the work of Dau *et al.* [15]. It is based on the observation that the existence of a circuit of length k in the side-information digraph \mathcal{G} requires at most $k - 1$ transmissions to satisfy the demands of the corresponding k users. Therefore a collection of ν vertex disjoint circuits corresponds to a ‘saving’ of at least ν transmissions. The bound is stated as follows: Let $\nu(\mathcal{G})$ be the circuit-packing number of a graph \mathcal{G} of order n . Then

$$\text{minrk}_q(\mathcal{G}) \leq n - \nu(\mathcal{G}).$$

In [27] the following result is given, leading the authors to introduce the *partition multicast scheme*, which outperforms the circuit-packing number.

PROPOSITION 19. *Let \mathcal{G} be a graph of order n . Then*

$$\text{minrk}_q(\mathcal{G}) \leq n - \min_{v \in \mathcal{V}} \deg_O(v),$$

for any $q > n$.

The broadcast rate of an IC-instance \mathcal{I} [1] is defined as follows, with respect to a prime p .

DEFINITION 20. *Let $\mathcal{I} = (\mathcal{X}, f)$ be an IC instance. We denote by $\beta_t(\mathcal{I})$ the minimal number of symbols required to broadcast the information to all receivers, when the block length is t , over all possible extensions of \mathbb{F}_p , i.e.*

$$\beta_t(\mathcal{I}) = \inf_q \{N \mid \exists \text{ a } q\text{-ary index code of length } N \text{ for } \mathcal{I}\}.$$

Moreover we denote by $\beta(\mathcal{I})$ the limit

$$\beta(\mathcal{I}) = \lim_{t \rightarrow \infty} \frac{\beta_t(\mathcal{I})}{t} = \inf_t \frac{\beta_t(\mathcal{I})}{t}.$$

In the following, we will also use the notation $\beta(\mathcal{G})$ to indicate the broadcast rate of any instance that has \mathcal{G} as side-information graph.

The graph parameter $\text{minrk}_q(\mathcal{G})$ completely characterizes the length of an optimal linear index code. Bar-Yossef *et al.* [3, 4] showed that in various cases linear codes attain the optimal word length, and they conjectured that the minimum broadcast rate of a graph \mathcal{G} was $\text{minrk}_2(\mathcal{G})$ also for non-linear codes. Lubetzky and Stav in [20] disproved this conjecture.

In the works of Alon *et al.* [1] and Shanmugam *et al.* [23], it was shown that results based on partitioning the vertices of a graph \mathcal{G} in cliques lead to a family of stronger bounds on $\beta(\mathcal{G})$, starting with an LP relaxation called *fractional chromatic number* [1] and the stronger *fractional local chromatic number* [23]. In [24] the authors extended all these schemes to the case of hypergraphs.

4. On directed graphs with min-rank one less than the order. In the work of Dau *et al.* [15] the authors characterize the undirected graphs of order n having min-rank $n - 1$. Here we extend this result to include directed graphs over a sufficiently large field. Our result relies in part on the following lemma, which is a construction of a digraph \mathcal{G}' of minrank one less than a digraph \mathcal{G} , obtained from \mathcal{G} by contracting an arc.

LEMMA 21. *Let $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ be a directed graph of order n such that there exist $i_1, i_2 \in \mathcal{V}$ with*

- (1) $(i_1, i_2) \in \mathcal{E}$ and $(i_2, i_1) \notin \mathcal{E}$
- (2) $\deg_O(i_1) = 1$.

Let $\mathcal{G}' = (\mathcal{V}', \mathcal{E}')$ with $\mathcal{V}' = \mathcal{V} \setminus \{i_1\}$ and $\mathcal{E}' = (\mathcal{E} \cup \{(j, i_2) \mid (j, i_1) \in \mathcal{E}\}) \setminus (\{(i_1, i_2)\} \cup \{(j, i_1) \mid (j, i_1) \in \mathcal{E}\})$. Then

$$\text{minrk}_q(\mathcal{G}) = \text{minrk}_q(\mathcal{G}') + 1$$

for any q .

Proof. Let $M = (m_{i,j})$ be a matrix that fits \mathcal{G} of minimum rank. We may assume that $i_1 = 1$ and $i_2 = 2$ so that the first two rows of M are

$$M_1 = (1, \alpha, 0, \dots, 0)$$

and

$$M_2 = (0, 1, m_{2,3}, \dots, m_{2,n}).$$

If $\alpha = 0$ then it is easy to check that deleting the first row and the first column of M we obtain M' of rank $\text{rank}(M) - 1$ that fits \mathcal{G}' .

Now suppose that $\alpha \neq 0$. We may assume that the rows $M_1, M_2, \dots, M_{\text{minrk}_q(\mathcal{G})}$ are linearly independent.

For each vertex $i \in \mathcal{V} \setminus \{1\}$, label the corresponding vertex in \mathcal{V}' by $i - 1$. Then construct the $(n - 1) \times (n - 1)$ matrix M' whose i -th row is obtained from the $i + 1$ -th row of M in the following way: for $i = 1, \dots, \text{minrk}_q(\mathcal{G}) - 1$ let

$$M'_i = (m_{i+1,1} + m_{i+1,2}, m_{i+1,3}, \dots, m_{i+1,n}),$$

and for $i = \text{minrk}_q(\mathcal{G}), \dots, n - 1$ we define

$$M'_i = (m_{i+1,1} + m_{i+1,2} - \lambda_1(1 + \alpha), m_{i+1,3}, \dots, m_{i+1,n})$$

where $\lambda_1 \in \mathbb{F}_q$ satisfies $M_{i+1} = \sum_{r=1}^{\text{minrk}_q(\mathcal{G})} \lambda_r M_r$ for some λ_r . The matrix M' fits \mathcal{G}' , so

$$\text{minrk}_q(\mathcal{G}') \leq \text{rank}(M') \leq \text{minrk}_q(\mathcal{G}) - 1.$$

Conversely, let $M' = (m'_{i,j})$ be a matrix that fits \mathcal{G}' having rank $\text{minrk}_q(\mathcal{G}')$ and suppose the rows $M'_1, M'_2, \dots, M'_{\text{minrk}_q(\mathcal{G}')}$ are linearly independent. Let $I = \{j \mid (j, 1) \in \mathcal{E}\}$ be the set of vertices of \mathcal{G} with outgoing arcs directed to 1. We construct the matrix M such that

$$M_1 = (1, -1, 0, \dots, 0),$$

$$M_i = (m'_{i-1,1}, 0, m'_{i-1,2}, \dots, m'_{i-1,n-1}),$$

for $i \in I \cap \{2, \dots, \text{minrk}_q(\mathcal{G}') + 1\}$ and

$$M_i = (0, m'_{i-1,1}, m'_{i-1,2}, \dots, m'_{i-1,n-1}),$$

for $i \in ([n] \setminus I) \cap \{2, \dots, \text{minrk}_q(\mathcal{G}') + 1\}$. For $i > \text{minrk}_q(\mathcal{G}') + 1$ we have that the $i - 1$ -th row of M' is given by

$$M'_{i-1} = \sum_{r=1}^{\text{minrk}_q(\mathcal{G}')} \lambda_r M'_r,$$

for some $\lambda_r \in \mathbb{F}_q$. If $i \in I$, we put

$$M_i = (m'_{i-1,1}, 0, m'_{i-1,2}, \dots, m'_{i-1,n-1})$$

and hence obtain

$$M_i = \lambda M_1 + \sum_{r=2}^{\text{minrk}_q(\mathcal{G}')+1} \lambda_{r-1} M_r$$

where the λ_r are the coefficients in the linear combination of M'_{i-1} , with respect to the first $\text{minrk}_q(\mathcal{G}')$ rows of M' , and $\lambda = \sum_{r \notin I} \lambda_{r-1} m'_{r-1,1}$. If $i \notin I$ we set

$$M_i = (0, m'_{i-1,1}, m'_{i-1,2}, \dots, m'_{i-1,n-1})$$

and we have

$$M_i = \lambda M_1 + \sum_{r=2}^{\text{minrk}_q(\mathcal{G}')+1} \lambda_{r-1} M_r$$

where $\lambda = -\sum_{r \in I} \lambda_{r-1} m'_{r-1,1}$.

Then M fits \mathcal{G} and

$$\text{minrk}_q(\mathcal{G}) \leq \text{rank}(M) \leq \text{minrk}_q(\mathcal{G}') + 1.$$

□

Note that the digraph \mathcal{G}' of Lemma 21 is the contraction of the digraph \mathcal{G} along the arc (i_1, i_2) .

EXAMPLE 22. Let \mathcal{G} and \mathcal{G}' be the two digraphs shown in Figure 1. The nodes 1 and 2 of \mathcal{G} satisfy the conditions of Lemma 21, so we can reduce \mathcal{G} to \mathcal{G}' . Consider the matrix

$$M = \begin{bmatrix} 1 & -1 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \\ 1 & 0 & 1 & 1 \end{bmatrix},$$

which fits \mathcal{G} . We have $M_3 = M_4 = M_1 + M_2$, constructing M' as in the lemma above we obtain

$$M' = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}.$$

M' fits \mathcal{G}' . Conversely, from M' we obtain M , and $\text{rank}(M) = \text{rank}(M') + 1$.

LEMMA 23. Let \mathcal{G} be a directed graph of order n such that $\tau(\mathcal{G}) = 2$. Then $\text{minrk}_q(\mathcal{G}) = n - 2$, for any $q > n$.

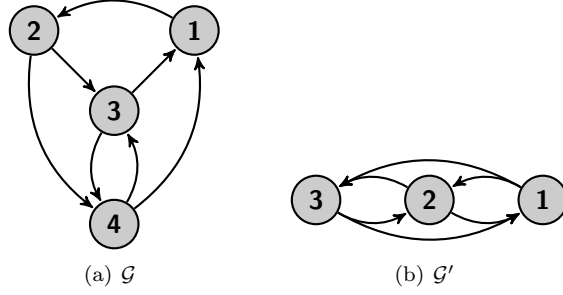


FIGURE 1. Contraction graph

Proof. As observed in Theorem 18, $n - \tau(\mathcal{G}) \leq \text{minrk}_q(\mathcal{G})$, so we need only to prove that $\text{minrk}_q(\mathcal{G}) \leq n - 2$.

We may suppose without loss of generality that there does not exist $i \in \mathcal{V}$ with out-degree less than 1, otherwise, from Lemma 21 we can delete the node i and consider the induced subgraph \mathcal{G}' , which satisfies $\text{minrk}_q(\mathcal{G}') = \text{minrk}_q(\mathcal{G}) - 1$.

Since $\tau(\mathcal{G}) = 2$, we have $\nu(\mathcal{G}) \in \{1, 2\}$. Since $\text{minrk}_q(\mathcal{G}) \leq n - \nu(\mathcal{G})$, if $\nu(\mathcal{G}) = 2$ then we have our claim immediately. Assume then that $\nu(\mathcal{G}) = 1$. We apply Lemma 21, iteratively. Note that each time we reduce a graph \mathcal{G} by an appropriate arc contraction, we obtain \mathcal{G}' with $\tau(\mathcal{G}') = 2$ and $\nu(\mathcal{G}') = 1$. Moreover, for each contraction of an arc of the graph, we only shorten the circuits that pass through the node that we delete, and we do not create any new circuit from the fact that the out-degree of the node is 1.

At the point that Lemma 21 is no longer applicable, there are two possible cases:

- 1) the out-degree of each node of the reduced graph \mathcal{G}' is at least 2,
- 2) there exists i_1 with out-degree 1 and $(i_1, i_2), (i_2, i_1) \in \mathcal{E}'$.

This last case is not possible, in fact if we consider the circuit $C = (i_1, i_2)$, from $\tau(\mathcal{G}') = 2$ we have that there exists a circuit C' which remains after deleting i_2 . Then, C' does not pass through i_1 otherwise it has to pass through i_2 . Then C and C' are disjoint, but this is not possible because $\nu(\mathcal{G}') = 1$.

Therefore, reducing \mathcal{G} we obtain \mathcal{G}' with k fewer nodes and all nodes have out-degree at least 2. Then from Proposition 19 and Lemma 21 it follows that

$$\text{minrk}_q(\mathcal{G}) = \text{minrk}_q(\mathcal{G}') + k \leq n - 2.$$

□

COROLLARY 24. *Let \mathcal{G} be a directed graph of order n such that $\tau(\mathcal{G}) = 2$. Then for any $q > n$, $\text{minrk}_q(\mathcal{G}) = \beta(\mathcal{G})$.*

We have now our main result of this section.

COROLLARY 25. *Let \mathcal{G} a graph of order n and let $q > n$. Then $\text{minrk}_q(\mathcal{G}) = n - 1$ if and only if $\tau(\mathcal{G}) = 1$. Moreover in that case we have $\beta(\mathcal{G}) = n - 1$ if and only if $\tau(\mathcal{G}) = 1$.*

Proof. If $\tau(\mathcal{G}) = 1$ then $\nu(\mathcal{G}) = 1$ and we have $\text{minrk}_q(\mathcal{G}) = n - 1$.

Conversely towards a contradiction assume that $\tau(\mathcal{G}) \geq 2$. Then consider a subgraph \mathcal{G}' of \mathcal{G} with $\tau(\mathcal{G}') = 2$. From Lemma 23 we have our claim. □

This last theorem implies that the problem of deciding whether or not a digraph has min-rank $n - 1$, over a sufficiently large field, can be solved in polynomial time,

using a depth-first search algorithm (see for instance [12]) that verifies in a polynomial time whether or not a graph is acyclic.

COROLLARY 26. *Let \mathcal{G} be a digraph of order n and $q > n$. Then deciding whether $\text{minrk}_q(\mathcal{G}) = n - 1$ can be done in polynomial time ($\mathcal{O}(n^3)$).*

REMARK 27. *In the final stages of the writing of this paper we learned of Ong’s result [21]. In fact Lemma 23, (although obtained independently) and its immediate corollary follows from [21, Theorem 1], which is a stronger result, since it holds without any restrictions on q . That is,*

THEOREM 28 ([21]). *Let \mathcal{G} be a directed graph of order n satisfying $\tau(\mathcal{G}) \leq 2$. Then*

$$\text{minrk}_q(\mathcal{G}) = \beta(\mathcal{G}) = n - \tau(\mathcal{G}).$$

The proof of Theorem 28 relies on showing that \mathcal{G} contains a particular subgraph \mathcal{G}_{sub} and then devising a coding scheme for \mathcal{G} based on the existence of \mathcal{G}_{sub} . The proof given in [21] is a non-trivial graph-theoretic proof and goes through a careful case-by-case analysis. The proof of Lemma 23 given here is rather more straightforward, being based on the construction of a new graph \mathcal{G}' obtained by iterative contractions of the original graph \mathcal{G} , following from Lemma 21. Such a result could be helpful also to decrease the size of a graph and thus to optimize the computation of the min-rank of the graph. The hypothesis that $q > n$ follows since we invoke the partition multicast solution (Proposition 19), therefore requiring the existence of a maximum distance separable code.

In the following table we report the values of the min-rank for graphs and directed graphs with near-extreme min-rank (i.e. 1, 2, $n - 2$, $n - 1$ and n).

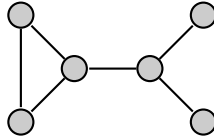


FIGURE 2. Forbidden subgraph

Minrank	Graph \mathcal{G}	Digraph \mathcal{D}
1	\mathcal{G} is complete (trivial)	\mathcal{D} is complete (trivial)
2	\mathcal{G} is 2 colorable [22]	for $q = 2$, if \mathcal{D} is 3-fair colorable [15]
$n - 2$	\mathcal{G} has maximum matching 2 and does not contain the graph in Figure 2 [15]	unknown
$n - 1$	\mathcal{G} is a star graph [15]	for $q > n$, $\tau(\mathcal{D}) = 1$ Corollary 25 for any q , $\tau(\mathcal{D}) = 1$ Theorem 28
n	\mathcal{G} has no edges (trivial)	\mathcal{D} is acyclic (trivial) [3]

5. A bound from t-designs. In this section we study the case for which an incidence structure, in particular a $2-(r^2+r+1, r+1, 1)$ or projective plane, arises from the side information. This yields an immediate upper bound on the min-rank of the hypergraph, based on known results on the ranks of incidence matrices. Furthermore, we show that secrecy and privacy are attainable for such configurations. Towards secrecy, we show that if an instance fits a projective plane, then a receiver may recover only its requested data, and no more. On the matter of privacy, we identify a constraint on the side information of an adversary hearing the broadcast such that it cannot access the receivers' requested data. We may assume without loss of generality that $t = 1$.

DEFINITION 29. We said that an instance, $\mathcal{I} = (\mathcal{X}, f)$, of the ICSI problem contains an incidence structure $\mathcal{S} = (\mathcal{P}, \mathcal{B})$ if

1) $\mathcal{P} = [n]$ and $|\mathcal{B}| \leq m$;

2) for each $i \in [m]$ there exists $B \in \mathcal{B}$ such that $f(i) \in B$ and $B \setminus \{f(i)\} \subseteq \mathcal{X}_i$.

Moreover we said that the instance coincides with the incidence structure \mathcal{S} if the following condition is satisfied.

2') for each $i \in [m]$ there exists $B \in \mathcal{B}$ such that $f(i) \in B$ and $B \setminus \{f(i)\} = \mathcal{X}_i$.

We immediately obtain the following proposition.

PROPOSITION 30. Let $\mathcal{I} = (\mathcal{X}, f)$ be an instance of ICSI problem and \mathcal{H} let be the corresponding hypergraph. If the instance contains a $2-(n, k, \lambda)$ design $\mathcal{D} = (\mathcal{P}, \mathcal{B})$ then for all q a power of a prime p such that p divides the order of \mathcal{D} it holds that

$$\text{minrk}_q(\mathcal{H}) \leq \frac{m+1}{2}.$$

Proof. Let D be the incidence matrix of \mathcal{D} . Then for the Theorem 4 we have that the p -rank of D is less or equal to $\frac{m+1}{2}$.

Now, it is easy to check that D fits \mathcal{H} , so

$$\text{minrk}_q(\mathcal{H}) \leq \text{rank}_q(D) \leq \text{rank}_p(D)$$

and that concludes the proof. \square

REMARK 31. To compute the min-rank of a hypergraph is an NP-hard problem [22], however, if there exists a 2-design as in Proposition 30 it is possible to have a bound on this value and we can use the linearly independent rows of its incidence matrix to decrease the number of transmissions. We remark further that this result does not require q to be large, and shows the existence of a class of instances with transmission rate much less than predicted by other bounds. For example, it is known that if an instance fits the incidence matrix of a projective plane of order r and $q > r^2 + r + 1$ then $\text{minrk}_q(\mathcal{H}) \leq r^2 + r + 1 - r = r^2 + 1$ (see, for example [5]), which is significantly greater than the bound $\text{minrk}_q(\mathcal{H}) \leq (r^2 + r + 2)/2$, given by Proposition 30.

EXAMPLE 32. Consider the instance of the ICSI problem \mathcal{I} given by $n = m = 7$, and $f(i) = i$ for $i = 1, \dots, 7$. Let the side information be

$$\begin{aligned} \mathcal{X}_1 &= \{2, 3\}, \mathcal{X}_2 = \{6, 7\}, \mathcal{X}_3 = \{5, 7\}, \mathcal{X}_4 = \{2, 5\}, \\ \mathcal{X}_5 &= \{1, 6\}, \mathcal{X}_6 = \{3, 4\}, \mathcal{X}_7 = \{1, 4\}. \end{aligned}$$

Consider the blocks

$$B_1 = \{1, 2, 3\}, B_2 = \{2, 6, 7\}, B_3 = \{3, 5, 7\}, B_4 = \{2, 4, 5\},$$

$$B_5 = \{1, 5, 6\}, B_6 = \{3, 4, 6\}, B_7 = \{1, 4, 7\}.$$

These blocks form the Fano plane as in Figure 3. This is a $2-(7, 3, 1)$ design of order 2 and the design is contained in the side information. The 2-rank of the design is 4. Then we can consider 4 linearly independent rows of the incidence matrix of the Fano plane, and encode the message using those reducing the number of transmissions from 7 to 4.

It can be checked that distribution of the ranks of the matrices that fit this incidence is given by

$$(4, 1), (5, 238), (6, 6575), (7, 9570),$$

thus the bound is sharply met in this instance. Moreover, an optimal encoding matrix L for this instance must have row space spanned by the rows of this incidence matrix; there is a unique optimal solution, up to left multiplication by an invertible matrix.

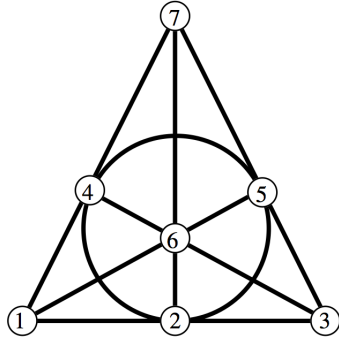


FIGURE 3. Fano plane

Now we consider the case when an instance $\mathcal{I} = (\mathcal{X}, f)$ of the ICSI problem contains a $2-(r^2 + r + 1, r + 1, 1)$ design, and the matrix corresponding to the index code is composed of the linearly independent rows of the incidence matrix of the design. We recall that a $2-(r^2 + r + 1, r + 1, 1)$ design has order r and the code of the design over \mathbb{F}_p , with p a prime divisor of r , has minimum distance equal to $r + 1$ (Theorem 5).

THEOREM 33. *If the instance \mathcal{I} of the ICSI problem coincides with the $2-(r^2 + r + 1, r + 1, 1)$ design, then no receiver $i \in [m]$ can recover a message X_j with $j \notin \mathcal{X}_i \cup \{f(i)\}$.*

Proof. Let \mathcal{D} be the $2-(r^2 + r + 1, r + 1, 1)$ design. Suppose that R_i wants to recover X_j with $j \notin \mathcal{X}_i \cup \{f(i)\}$. From Lemma 16 it is able to do so if and only if there exists a vector $\mathbf{u} \in \mathbb{F}_p^n$, $n = r^2 + r + 1$, such that $\text{Supp}(\mathbf{u}) \subseteq \mathcal{X}_i \cup \{f(i)\}$ and $\mathbf{u} + \mathbf{e}_j \in C_p(\mathcal{D})$. If this vector is a codeword of the code, at least $r + 1$ positions are different from 0. Now consider the vector $\mathbf{1}_{\mathcal{X}_i} + \mathbf{e}_{f(i)} \in C_p(\mathcal{D})$, where $\mathbf{1}_{\mathcal{X}_i}$ is the vector in \mathbb{F}_p^n with 1's in the positions contained in \mathcal{X}_i . We have $|\text{Supp}(\mathbf{u} + \mathbf{e}_j) \cap \text{Supp}(\mathbf{1}_{\mathcal{X}_i} + \mathbf{e}_{f(i)})| \geq r$ and also there are at least 2 positions of $\mathbf{u} + \mathbf{e}_j$ in this intersection that have the same value (we can use only the $p - 1$ values of $\mathbb{F}_p \setminus \{0\}$ for these r positions). Suppose that this value is $\alpha \in \mathbb{F}_p \setminus \{0\}$, then we have $d(\mathbf{u} + \mathbf{e}_j, \alpha(\mathbf{1}_{\mathcal{X}_i} + \mathbf{e}_{f(i)})) \leq r$. So $\mathbf{u} + \mathbf{e}_j$ is not a codeword of $C_p(\mathcal{D})$, which means that R_i is not able to recover X_j . \square

Encoding with a matrix whose row space contains the blocks of a projective plane guarantees the secrecy of the transmission.

Assume, now, the presence of an adversary A who can listen to all transmissions. The adversary is assumed to possess side information $\{X_h \mid h \in \mathcal{X}_A \subseteq [n]\}$. In [13], it is shown that for a transmission matrix L for a linear index code representing $\mathcal{I} = (\mathcal{X}, f)$, if $|\mathcal{X}_A| \leq d - 2$, where d is the minimum distance of the code $\langle L \rangle$, then A is not able to recover an element X_j with $j \notin \mathcal{X}_A$.

Consider now an instance $\mathcal{I} = (\mathcal{X}, f)$ of the ICSI problem containing a $2-(p^2 + p + 1, p + 1, 1)$ design, where p is a prime number. Suppose the matrix L as above is used as an encoding matrix. Then we obtain the following result.

THEOREM 34. *If $|\mathcal{X}_A| \leq 2p - 2$ and for each block B of the design $|\mathcal{X}_A \cap B| \leq p - 1$, then A is not able to recover X_j for any $j \notin \mathcal{X}_A$.*

Proof. If p is even, then the result follows from the fact that $|\mathcal{X}_A| \leq 1 = d - 2$. Let p be odd. We know from Theorem 6 that in the code generated by the incidence matrix of a $2-(p^2 + p + 1, p + 1, 1)$ design there are no codewords with weights in $[p + 2, 2p - 1]$. To recover the message X_j , A needs a codeword of weight $p + 1$. Such codewords are those corresponding to some block B , that is a vector of the form

$$\sum_{i \in B} \mathbf{e}_i$$

and its scalar multiples.

So A recovers X_j if and only if there exists $\mathbf{u} + \mathbf{e}_j \in C$ with $\text{Supp}(\mathbf{u}) \subset \mathcal{X}_A$ and $|\text{Supp}(\mathbf{u})| = p$. Here C means the code of the projective space. Then $\text{Supp}(\mathbf{u} + \mathbf{e}_j) = B$ for some block B , and so $|\mathcal{X}_A \cup \{j\} \cap B| \geq p + 1$. \square

6. Index Coding with Coded Side Information. In [26] the authors generalized the index coding problem so that coded packets of a data matrix X may be broadcast or part of a user's cache. This finds applications, for example, in broadcast channels with helper relay nodes. We present the model with coded side information in the following section.

6.1. Preliminaries on the ICCSI Problem. As before there is a data matrix $X \in \mathbb{F}_q^{n \times t}$ and a set of m receivers or users. For each $i \in [m]$, the i th user seeks some linear combination of X , say $R_i X$ for some $R_i \in \mathbb{F}_q^n$. A user's cache comprises a pair of matrices

$$V^{(i)} \in \mathbb{F}_q^{d_i \times n} \text{ and } \Lambda^{(i)} \in \mathbb{F}_q^{d_i \times t}$$

related by the equation

$$\Lambda^{(i)} = V^{(i)} X.$$

While X is unknown to user i , it is assumed that any vector v in the row spaces of $V^{(i)}$ and the respective $\lambda = vX$ can be generated at the i th receiver. We denote these respective row spaces by $\mathcal{X}^{(i)} := \langle V^{(i)} \rangle$ and $\mathcal{L}^{(i)} := \{v \cdot X \mid v \in \mathcal{X}^{(i)}\}$ for each i . The side information of the i th user is $(\mathcal{X}^{(i)}, \mathcal{L}^{(i)})$. Similarly, the sender has the pair of row spaces $(\mathcal{X}^{(S)}, \mathcal{L}^{(S)})$ for matrices

$$V^{(S)} \in \mathbb{F}_q^{d_S \times n} \text{ and } \Lambda^{(S)} = V^{(S)} X \in \mathbb{F}_q^{d_S \times t}$$

and does not necessarily possess X itself.

The i th user requests a coded packet $R_i X \in \mathcal{L}^{(S)}$ with $R_i \in \mathcal{X}^{(S)} \setminus \mathcal{X}^{(i)}$. We denote by R the $m \times n$ matrix over \mathbb{F}_q with each i th row equal to R_i . The matrix R thus represents the requests of all m users. We denote by

$$\mathcal{X} := \{A \in \mathbb{F}_q^{m \times n} : A_i \in \mathcal{X}^{(i)}, i \in [m]\},$$

so that $\mathcal{X} = \oplus_{i \in [m]} \mathcal{X}^{(i)}$ is the direct sum of the $\mathcal{X}^{(i)}$ as a vector space over \mathbb{F}_q . Similarly, we write $\oplus \mathcal{X}^{(S)} := \oplus_{i \in [m]} \mathcal{X}^{(S)} = \{Z \in \mathbb{F}_q^{m \times n} : Z_i \in \mathcal{X}^{(S)}\}$.

For the remainder, we let $\mathcal{X}, \mathcal{X}^{(S)}, \oplus \mathcal{X}^{(S)}, R$ be as defined above and write $\mathcal{I} = (\mathcal{X}, \mathcal{X}^{(S)}, R)$ to denote an instance of the ICCSI problem for these parameters. As before, for the ICCSI instance $\beta_t(\mathcal{I})$ denotes the minimum broadcast rate for block-length t where the encoding is over all possible extensions of \mathbb{F}_p . That is, for $\mathcal{I} = (\mathcal{X}, \mathcal{X}^{(S)}, R)$

$$\beta_t(\mathcal{I}) = \inf_q \{N \mid \exists \text{ a } q\text{-ary index code of length } N \text{ for } \mathcal{I}\}.$$

The optimal broadcast rate is given by the limit

$$\beta(\mathcal{I}) = \lim_{t \rightarrow \infty} \frac{\beta_t(\mathcal{I})}{t} = \inf_t \frac{\beta_t(\mathcal{I})}{t}.$$

DEFINITION 35. Let N be a positive integer. We say that the map

$$E : \mathbb{F}_q^{n \times t} \rightarrow \mathbb{F}_q^N,$$

is an \mathbb{F}_q -code for $\mathcal{I} = (\mathcal{X}, \mathcal{X}^{(S)}, R)$ of length N if for each i th receiver, $i \in [m]$ there exists a decoding map

$$D_i : \mathbb{F}_q^N \times \mathcal{X}^{(i)} \rightarrow \mathbb{F}_q^t,$$

satisfying

$$\forall X \in \mathbb{F}_q^{n \times t} : D_i(E(X), A) = R_i X,$$

for some vector $A \in \mathcal{X}^{(i)}$, in which case we say that E is an \mathcal{I} -IC. E is called an \mathbb{F}_q -linear \mathcal{I} -IC if $E(X) = LV^{(S)}X$ for some $L \in \mathbb{F}_q^{N \times ds}$, in which case we say that L represents the code E .

Given an instance $\mathcal{I} = (\mathcal{X}, \mathcal{X}^{(S)}, R)$ and a matrix $L \in \mathbb{F}_q^{N \times ds}$ that represents an \mathcal{I} -IC, we write \mathcal{L} to denote the space $\langle LV^{(S)} \rangle$.

We have the following (see [5, 26]).

LEMMA 36. Let $L \in \mathbb{F}_q^{N \times ds}$. Then L represents a \mathbb{F}_q -linear \mathcal{I} -IC index code of length N if and only if for each $i \in [m]$, $R_i \in \mathcal{L} + \mathcal{X}^{(i)}$.

REMARK 37. If the equivalent conditions of the above lemma hold we have that for each $i \in [m]$, $R_i = \mathbf{b}^{(i)}LV^{(S)} + \mathbf{a}^{(i)}V^{(i)}$ for some vectors $\mathbf{a}^{(i)}, \mathbf{b}^{(i)}$. So User i decodes its request by computing

$$R_i X = \mathbf{b}^{(i)}LV^{(S)}X + \mathbf{a}^{(i)}V^{(i)}X = \mathbf{b}^{(i)}Y + \mathbf{a}^{(i)}\Lambda^{(i)},$$

where Y is the received message.

REMARK 38. The ICCSI problem as introduced before is indeed a special case of the ICCSI problem. Setting $V^{(S)}$ to be the $n \times n$ identity matrix, $R_i = \mathbf{e}_{f(i)}$ and $V^{(i)}$ to be the $d_i \times n$ matrix with rows $V_j^{(i)} = \mathbf{e}_{i_j}$ for each $i_j \in \mathcal{X}_i$ yields $\mathcal{X}^{(i)} = \langle \mathbf{e}_j : j \in \mathcal{X}_i \rangle$, so that $\text{Supp}(\mathbf{v}) \subset \mathcal{X}_i$ if and only if $\mathbf{v} \in \mathcal{X}^{(i)}$.

The analogue of the min-rank is as follows:

DEFINITION 39 ([5]). *The min-rank of the instance $\mathcal{I} = (\mathcal{X}, \mathcal{X}^{(S)}, R)$ of the ICCSI problem over \mathbb{F}_q is*

$$\kappa(\mathcal{I}) = \min \left\{ \text{rank}(A + R) : \begin{array}{l} A \in \mathbb{F}_q^{m \times n}, \\ A_i \in \mathcal{X}^{(i)} \cap \mathcal{X}^{(S)}, \forall i \in [m] \end{array} \right\}.$$

Note that $\kappa(\mathcal{I})$ measures the rank distance of the $m \times n$ matrix R to the \mathbb{F}_q -linear matrix code $\mathcal{X} \cap (\oplus \mathcal{X}^{(S)})$.

As in the ICSI case, the length of an optimal \mathbb{F}_q -linear ICCSI index code is characterized by the min-rank of the instance.

LEMMA 40 ([5]). *The length of an optimal \mathbb{F}_q -linear index code for $\mathcal{I} = (\mathcal{X}, \mathcal{X}^{(S)}, R)$ is $\kappa(\mathcal{I})$.*

6.2. Approaches from Integer and Linear Programming. In this section we generalize all the bounds given in [24] (which themselves are generalizations of [27]) to the case of the ICCSI problem. We start with the following definition, introduced in [26] as a *coding group*, wherein a procedure to detect such as subset is given. It is easy to see that this definition generalizes the definition of a hyperclique for the ICSI case given in [24].

DEFINITION 41. *Let $\mathcal{I} = (\mathcal{X}, \mathcal{X}^{(S)}, R)$ be an instance of the ICCSI problem. A subset of receivers $C \subseteq [m]$ is called generalized clique if there exists $\mathbf{v} \in \mathcal{X}^{(S)}$ such that $R_i \in \langle \mathbf{v} \rangle + \mathcal{X}^{(i)}$ for all $i \in C$.*

We have the following characterisation of a generalized clique is immediate from the definition.

LEMMA 42. *Let $\mathcal{I} = (\mathcal{X}, \mathcal{X}^{(S)}, R)$ be an instance of the ICCSI problem. $C \subseteq [m]$ is a generalized clique if and only if either of the following equivalent conditions hold:*

1. *there exists $\mathbf{v} \in \mathcal{X}^{(S)}$ such that $\langle \mathbf{v} \rangle \subset \langle R_i \rangle + \mathcal{X}^{(i)}$ for all $i \in C$,*
2. *$\text{rank}(R_C + A_C) = 1$ for some $m \times n$ matrix $A \in \mathcal{X} \cap (\oplus \mathcal{X}^{(S)})$.*

For simplicity in the following we refer to a generalized clique just as a clique.

The demand $R_i X$ of each user i of a clique can be met by sending the message $\mathbf{v}X$ and hence a set of ℓ cliques that partitions the set $[m]$ ensures that all requests can be delivered in at most ℓ transmissions. Minimizing this number for a specific instance can be found via integer programming (see [7, 27, 24]). Recall that the optimal solution of the LP-relaxation of an IP problem returns rational values.

DEFINITION 43. *We denote by \mathcal{C} the set of all cliques of $\mathcal{I} = (\mathcal{X}, \mathcal{X}^{(S)}, R)$. For each clique $C \in \mathcal{C}$ define the set*

$$\mathcal{R}(C) := \{ \mathbf{v} \in \mathbb{F}_q^n \mid R_i \in \langle \mathbf{v} \rangle + \mathcal{X}^{(i)} \forall i \in C \}.$$

DEFINITION 44. *We define the generalized clique cover number of \mathcal{I} , denoted by $\varphi(\mathcal{I})$, to be the optimal solution of the following integer programme:*

$$\begin{aligned} & \min \sum_{C \in \mathcal{C}} y_C \\ & \text{s.t.} \quad \sum_{C: j \in C} y_C = 1 \text{ for all } j \in [m] \end{aligned}$$

$$(3) \quad y_C \in \{0, 1\} \text{ for all } C \in \mathcal{C}.$$

The LP relaxation of (3) (so with the relaxed constraint $0 \leq y_C \leq 1$ for all C) is the fractional generalized clique cover number $\varphi_f(\mathcal{I})$.

DEFINITION 45. For each $C \in \mathcal{C}$ fix a vector $\mathbf{v}_C \in \mathcal{R}(C)$. We define the following integer programme with respect to the vectors \mathbf{v}_C .

$$\min k$$

$$\begin{aligned} \text{s.t.} \quad & \sum_{C: \mathbf{v}_C \notin \mathcal{X}^{(j)}} y_C \leq k \text{ for all } j \in [m] \\ & \sum_{C: j \in C} y_C = 1 \text{ for all } j \in [m] \end{aligned}$$

$$(4) \quad y_C \in \{0, 1\} \text{ for all } C \in \mathcal{C} \text{ and } k \in \mathbb{N}.$$

We denote by $\phi_l(\mathcal{I}, (\mathbf{v}_C \in \mathcal{R}(C) : C \in \mathcal{C}))$ the optimal solution of (4), depending on the fixed \mathbf{v}_C 's. The minimum over all possible \mathbf{v}_C 's is called the local generalized clique cover number

$$\varphi_l(\mathcal{I}) = \min_{(\mathbf{v}_C \in \mathcal{R}(C) : C \in \mathcal{C})} \phi_l(\mathcal{I}, (\mathbf{v}_C : C \in \mathcal{C})).$$

This is an extension of the local hyperclique cover: for a set of fixed \mathbf{v}_C , given user $j \in [m]$ and some feasible solution to (3), count number of cliques C in that generalized clique cover such that \mathbf{v}_C is not contained in the side-information $\mathcal{X}^{(j)}$ and let k be the maximum number of such cliques for each j . The optimal solution of (4) is the minimum value of k over all possible solutions of (3) and all choices of \mathbf{v}_C . The minimum of the LP relaxation of (4) over all possible \mathbf{v}_C 's is called the fractional local generalized clique cover number $\varphi_{lf}(\mathcal{I})$. Both $\varphi_{lf}(\mathcal{I})$ and $\varphi_l(\mathcal{I})$ will be shown to give upper bound on the transmission rate of the instance \mathcal{I} .

REMARK 46. Consider the instance \mathcal{I} of the ICCSI problem with $m = n = 6$, $\mathbb{F}_q = \mathbb{F}_4 = \{0, 1, \alpha, \alpha^2\}$ and $\mathcal{X}^{(S)} = \mathbb{F}_4^6$, where α is such that $\alpha^2 = \alpha + 1$.

$$\begin{aligned} V^{(1)} &= \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{bmatrix}, V^{(2)} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 \end{bmatrix}, \\ V^{(3)} &= \begin{bmatrix} 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{bmatrix}, V^{(4)} = \begin{bmatrix} 0 & 0 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 & 0 \end{bmatrix}, \\ V^{(5)} &= \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 & 0 & 0 \end{bmatrix}, V^{(6)} = \begin{bmatrix} 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}, \end{aligned}$$

and $R_1 = 100000$, $R_2 = 010000$, $R_3 = 001000$, $R_4 = 000100$, $R_5 = 000010$, $R_6 = 000001$.

Now if we consider the partition $C_1 = \{1, 2\}$, $C_2 = \{3, 4\}$, $C_3 = \{5, 6\}$, and we use $\mathbf{v}_{C_1} = 110000$, $\mathbf{v}_{C_2} = 001100$, $\mathbf{v}_{C_3} = 00001\alpha$, to encode X , then we obtain $k = 3$. But using $\mathbf{v}_{C_3} = 000011$ we have that $k = 2$. Clearly the optimal solution of (4) depends on the choice of vectors \mathbf{v}_C .

Another approach is based on *partition multicast*, as described in [24].

DEFINITION 47. We define the partition generalized multicast number, $\varphi^p(\mathcal{I})$ to be the optimal solution of the following integer program

$$\begin{aligned}
& \min \sum_{M \subset [m]} a_M d_M \\
& \text{s.t.} \quad \sum_{M: j \in M} a_M = 1 \text{ for all } j \in [m] \\
& a_M \in \{0, 1\} \text{ for all } M \subset [m], M \neq \emptyset.
\end{aligned}$$

(5) and $d_M = \dim(\langle R_M \rangle) - \min_{j \in M} \dim(\langle R_M \rangle \cap \mathcal{X}^{(j)})$.

The LP relaxation of (5) is called the fractional partition generalized multicast number, $\varphi_f^p(\mathcal{I})$.

We remark that $d_M = \max_{j \in M} \dim(\langle R_M \rangle / \langle R_M \rangle \cap \mathcal{X}^{(j)})$. We briefly justify the above: each user is assigned to exactly one multicast group M , so the selected groups M form a partition of $[m]$. Each member j of a multicast group $M \subset [m]$ already has access to at least $\dim(\langle R_M \rangle \cap \mathcal{X}^{(j)})$ independent vectors in $\langle R_M \rangle$. As we'll show in Theorem 52, a coding scheme can be applied to ensure delivery of all remaining requests within a group using at most d_M transmissions. The total number of transmissions required by this scheme is the sum of the d_M , over all selected multicast groups M .

The final approach considered combines partition multicast and local clique covering [24, Definition 10]. The users $[m]$ are partitioned into multicast groups and independently covered by generalized cliques. Each multicast group offers a reduced ICCSI problem, to which a restricted local clique cover is applied.

DEFINITION 48. Define the following integer programme

$$\begin{aligned}
& \min \sum_{M \subset [m]} a_M t_M \\
& \text{s.t.} \quad \sum_{\substack{C: \mathbf{v}_C \notin \mathcal{X}^{(j)} \\ C \cap M \neq \emptyset}} y_C \leq t_M \text{ for all } j \in M \\
& \sum_{M: j \in M} a_M = 1, \quad \sum_{C: j \in C} y_C = 1 \text{ for all } j \in [m]
\end{aligned}$$

(6) $a_M, y_C \in \{0, 1\}$ for all $C \in \mathcal{C}$, $M \subset [m]$ and $t_M \in \mathbb{N}$.

We denote by $\phi_l^p(\mathcal{I}, (\mathbf{v}_C \in \mathcal{R}(C) : C \in \mathcal{C}))$ the optimal solution of (6) with respect to $(\mathbf{v}_C \in \mathcal{R}(C) : C \in \mathcal{C})$ fixed. The minimum over all possible choices of \mathbf{v}_C is called the partitioned local generalized clique cover number

$$\varphi_l^p(\mathcal{I}) = \min_{(\mathbf{v}_C \in \mathcal{R}(C) : C \in \mathcal{C})} \phi_l^p(\mathcal{I}, (\mathbf{v}_C \in \mathcal{R}(C) : C \in \mathcal{C})).$$

The minimum of the LP relaxation of (6) over all possible choices of \mathbf{v}_C is called the fractional partitioned local generalized clique cover number $\varphi_{lf}^p(\mathcal{I})$.

Now, we will show that achievable schemes exist for all parameters and hence obtain upper bounds on $\beta(\mathcal{I})$. The basic technique is to use MDS codes. It will be notationally convenient to express X as a column vector of length n over \mathbb{F}_{q^t} . We will assume in all cases that q^t is large enough to assure the existence of an \mathbb{F}_{q^t} -MDS code of the required length.

THEOREM 49. *Let $\mathcal{I} = (\mathcal{X}, \mathcal{X}^{(S)}, R)$. There exist achievable \mathbb{F}_q -linear index codes corresponding to $\varphi(\mathcal{I})$ and $\varphi_f(\mathcal{I})$. In particular, we have*

$$\beta(\mathcal{I}) \leq \varphi_f(\mathcal{I}) \leq \varphi(\mathcal{I}).$$

Proof. For each $C \in \mathcal{C}$ fix a vector $\mathbf{v}_C \in \mathcal{R}(C)$. Then given a clique cover $\mathcal{C}^{opt} = \{C \in \mathcal{C} : y_C = 1\}$, corresponding to an optimal solution of (3), and a data vector X , we broadcast $\{\mathbf{v}_C X : C \in \mathcal{C}^{opt}\}$. The demands $R_j X$ of each receiver $j \in [m]$ can be met in $|\mathcal{C}^{opt}| = \varphi(\mathcal{I})$ transmissions since $R_j \in \langle \mathbf{v}_C \rangle + \mathcal{X}^{(j)}$ for all $j \in C$.

Now consider the LP relaxation of (3) and let an optimal solution be given by $\{y_C : C \in \mathcal{C}\} \subset \mathbb{Q}$. Let r be the least common denominator of the y_C and for each C define the integral weight $\hat{y}_C = r y_C \in [r]$. Denote the resulting multi-set of cliques by $\mathcal{C}^{opt} = \{(\hat{y}_C, C) : C \in \mathcal{C}\}$. Every user j is contained in r (not necessarily distinct) cliques of \mathcal{C}^{opt} , with each distinct clique C appearing with multiplicity \hat{y}_C . Now split each packet $X_i \in \mathbb{F}_{q^t}$ into r packets of equal size, so consider now X as the data matrix

$$X = \begin{bmatrix} X_1^1 & \dots & X_1^r \\ \vdots & & \vdots \\ X_n^1 & \dots & X_n^r \end{bmatrix},$$

with coefficients in a subfield \mathbb{F}_{q^ℓ} of \mathbb{F}_{q^t} where ℓ is the least divisor of t satisfying $r\ell \leq t$. If $q^\ell > s = \sum_C \hat{y}_C$ then there exists an \mathbb{F}_{q^ℓ} - $[s, r]$ MDS code, so suppose this is the case and let G be a generator matrix of such a code. Now list the elements of \mathcal{C}^{opt} as C_1, \dots, C_s and assign to each column G^i of G the clique C_i .

For each clique C_i in \mathcal{C}^{opt} , the packet $\mathbf{v}_{C_i} X G^i \in \mathbb{F}_{q^t}$ is transmitted. Each transmission corresponds to an \mathbb{F}_q -linear combination of blocks of length $\ell \leq t/r$ over \mathbb{F}_q and there are $s = r\varphi_f(\mathcal{I})$ transmissions in total.

Now consider the receiver $j \in [m]$, which has demanded the vector $R_j X$. We may assume that j is contained in the first r cliques C_1, \dots, C_r of the list of s cliques. Then all users, including j , has received $(\mathbf{v}_{C_1} X G^1, \dots, \mathbf{v}_{C_r} X G^r) \in \mathbb{F}_{q^\ell}^r$. From Remark 37 we have $R_j = \alpha_i \mathbf{v}_{C_i} + \mathbf{a}_i V^{(j)}$ for some α_i, \mathbf{a}_i for each $i \in [r]$. Thus j can recover the vector

$$(R_j X G^1, \dots, R_j X G^r) = (\alpha_1 \mathbf{v}_{C_1} X G^1 + \mathbf{a}_1 V^{(j)} X G^1, \dots, \alpha_r \mathbf{v}_{C_r} X G^r + \mathbf{a}_r V^{(j)} X G^r).$$

Now

$$(R_j X G^1, \dots, R_j X G^r) = R_j X G^{[r]},$$

where $G^{[r]} = [G^1, \dots, G^r]$ is an invertible $r \times r$ matrix, by the MDS property of the code generated by G . Then j can decode $R_j X$. Every user receives the r packets it requires and the total number of transmissions is s .

THEOREM 50. *Let $\mathcal{I} = (\mathcal{X}, \mathcal{X}^{(S)}, R)$. There are achievable linear index codes corresponding to $\varphi_l(\mathcal{I})$ and $\varphi_{lf}(\mathcal{I})$ implying $\beta(\mathcal{I}) \leq \varphi_{lf}(\mathcal{I}) \leq \varphi_l(\mathcal{I})$.*

Proof. Let $\mathcal{C}^{opt} = \{C_1, \dots, C_s\}$ the set of cliques for which $y_C = 1$ in the optimal solution $(k, \{y_C : C \in \mathcal{C}\})$ of (4) for some fixed choice of vectors $\mathbf{v}_C \in \mathbb{F}_q^n$. Let

$s = \sum_C y_C = |\mathcal{C}^{opt}|$ and let G the generator matrix of an \mathbb{F}_q - $[s, k]$ MDS code. As before we associate a column of G to each clique in \mathcal{C}^{opt} , and the sender transmits an encoding of the data vector $X \in \mathbb{F}_q^{n \times 1}$ as:

$$Y = \sum_{C \in \mathcal{C}^{opt}} \mathbf{v}_C X G^C = G(\mathbf{v}_C X)_{C \in \mathcal{C}^{opt}},$$

which corresponds to s transmissions over \mathbb{F}_q . For any $j \in [m]$, the constraints in the integer programme of (4) require that there are at most k cliques of \mathcal{C}^{opt} with $\mathbf{v}_C \notin \mathcal{X}^j$. This means that for any choice of j , there are at most k vectors in $\{\mathbf{v}_C : C \in \mathcal{C}\}$ not contained in \mathcal{X}^j . We have

$$Y = \sum_{C \in \mathcal{C}^{opt}: \mathbf{v}_C \in \mathcal{X}^j} \mathbf{v}_C X G^C + \sum_{C \in \mathcal{C}^{opt}: \mathbf{v}_C \notin \mathcal{X}^j} \mathbf{v}_C X G^C.$$

Therefore, Receiver j , given its side information \mathcal{X}^j , can recover

$$\sum_{C \in \mathcal{C}^{opt}: \mathbf{v}_C \notin \mathcal{X}^j} \mathbf{v}_C X G^C = \tilde{G}(\mathbf{v}_C X)_{C \in \mathcal{C}^{opt}: \mathbf{v}_C \notin \mathcal{X}^j}$$

where

$$\tilde{G} = [G^C]_{C \in \mathcal{C}^{opt}: \mathbf{v}_C \notin \mathcal{X}^j}$$

is a $k \times k$ submatrix of G . Since \tilde{G} is invertible by the MDS property, the user j can retrieve the vector $(\mathbf{v}_C X)_{C \in \mathcal{C}^{opt}: \mathbf{v}_C \notin \mathcal{X}^j}$. For a clique C containing j , using $\mathbf{v}_C X$ it is possible to retrieve $R_j X$.

Now consider the LP relaxation of (4) and let $(k, \{y_C : C \in \mathcal{C}\})$ be an optimal solution for some rationals $0 \leq y_C \leq 1$. This time, let r be the least common denominator of the y_C and k and for each C define $\hat{y}_C = r y_C, \hat{k} = r k \in \mathbb{Z}$. As before, every distinct clique C is assigned an integer weight in $[r]$ and we denote the corresponding multi-set of cliques by \mathcal{C}^{opt} . Every user is contained in r cliques. Let $s = \sum_{C \in \mathcal{C}} \hat{y}_C$, let G and H be respective generator matrices of $[s, \hat{k}]$ and $[s, r]$ MDS codes over \mathbb{F}_q . Again we represent X as an $n \times r$ matrix with each packet X_i in the form of a vector of length r over a subfield of \mathbb{F}_q . Associating the i th columns of G and H to the i th clique C_i with respect to a fixed listing of the multi-set \mathcal{C}^{opt} , the following is transmitted.

$$Y = \sum_{i=1}^s (\mathbf{v}_{C_i} X H^i) G^i.$$

For any $j \in [m]$, the j th receiver uses its side information as before to obtain

$$\sum_{i=1}^{\hat{k}} (\mathbf{v}_{C_i} X H^i) G^i,$$

where without loss of generality, $C_1, \dots, C_{\hat{k}}$ are the cliques for which $\mathbf{v}_C \notin \mathcal{X}^j$. Moreover, j is in r of these cliques, which we may suppose to be C_1, \dots, C_r . So as before from the MDS property of G , j can recover the vector $(\mathbf{v}_{C_1} X H^1, \dots, \mathbf{v}_{C_{\hat{k}}} X H^{\hat{k}})$, and in particular $(\mathbf{v}_{C_1} X H^1, \dots, \mathbf{v}_{C_r} X H^r)$.

Since for each $i \in [r]$, $R_j = \alpha_i \mathbf{v}_{C_i} + \mathbf{a}_i V^{(j)}$ for some α_i and \mathbf{a}_i , the user j can obtain

$$(R_j X H^1, \dots, R_j X H^r),$$

and therefore obtain $R_j X$ by the MDS property of H . Every user receives its required r packets and the total number of transmissions is \hat{k} . \square

Given an instance $\mathcal{I} = (\mathcal{X}, \mathcal{X}^{(S)}, R)$, let \tilde{m} denote the number of distinct equivalence classes of $[m]$ under the relation $i \sim j$ if $\mathcal{X}^{(i)} = \mathcal{X}^{(j)}$. We will use the following result of [5], which generalizes Proposition 19.

PROPOSITION 51. *Let $\mathcal{I} = (\mathcal{X}, \mathcal{X}^{(S)}, R)$. If $q > \tilde{m}$ then $\kappa(\mathcal{I}) \leq \max\{n - d_i : i \in [m]\}$. For any q , $\kappa(\mathcal{I}) \leq \text{rank}(R)$.*

Proof. That $\kappa(\mathcal{I}) \leq \text{rank}(R)$ is trivial: $\kappa(\mathcal{I})$ is by definition the minimum rank of an element of the coset $R + \mathcal{X} \cap (\oplus \mathcal{X}^{(S)})$. Indeed, an \mathbb{F}_q -linear code of length $N = \text{rank}(R)$ exists simply by sending a basis of the rowspace of R , in which case no user requires its side-information in order to retrieve its request $R_i X$. That $\kappa(\mathcal{I}) \leq \max\{n - d_i : i \in [m]\}$ is shown in [5]. \square

The essential content of the proof of Proposition 51 is that there exists an $N \times n$ matrix L realizing \mathcal{I} for $N \leq \max\{n - d_i : i \in [m]\}$, which corresponds to a multicast solution, so every user can retrieve any linear combination of the X_i . In this case the matrix L is such that $\langle L \rangle + \mathcal{X}^{(i)} = \mathbb{F}_q^n$ for each i .

THEOREM 52. *Let $\mathcal{I} = (\mathcal{X}, \mathcal{X}^{(S)}, R)$. There are achievable linear index codes of lengths $\varphi^p(\mathcal{I})$ and $\varphi_f^p(\mathcal{I})$, which implies that $\beta(\mathcal{I}) \leq \varphi_f^p(\mathcal{I}) \leq \varphi^p(\mathcal{I})$.*

Proof. Let \mathcal{M} be a collection of multicast groups $M \subset [m]$ yielding an optimal solution to (5).

Let $M \in \mathcal{M}$ and consider the ICCSI instance $\mathcal{I}_M = (\oplus_{j \in M} \mathcal{X}^{(j)}, \langle R_M \rangle, R_M)$. From Proposition 51, for sufficiently large q , there exists $L_M \in \mathbb{F}_q^{d_M \times n}$ such that each user in M can decode $R_j X$, which uses d_M transmissions. Applying this approach to each $M \in \mathcal{M}$, we find that all users' requests can be retrieved using at most $\varphi^p(\mathcal{I}) = \sum_{M \in \mathcal{M}} d_M$ transmissions.

Let us consider now the LP relaxation of (5) and let $\{a_M : M \subset [m]\} \subset \mathbb{Q}$ be an optimal solution. Let r denote the least common denominator of the a_M and define $\hat{a}_M = r a_M \in \mathbb{Z}$. Every multicast group M is assigned an integer weight in $[r]$ and the multi-set of multicast groups is denoted by \mathcal{M}^{opt} . Every user is contained in r multicast groups of \mathcal{M}^{opt} . As before, we represent the data vector $X \in \mathbb{F}_{q^t}^n$ as an $n \times r$ matrix over a subfield of \mathbb{F}_{q^t} . Let L_M be an $d_M \times n$ matrix satisfying $\langle R_M \rangle \subset \langle L_M \rangle + \mathcal{X}^{(j)}$ for $j \in M$, i.e. such that each user assigned to M can retrieve its requested data $R_j X$. Let $s = \sum_M \hat{a}_M$ and, as before, let G be a generator matrix of an $[s, r]$ MDS code over \mathbb{F}_{q^ℓ} with $\ell r \leq t$ and associate a column G^i of G to each multicast group M_i in \mathcal{M} . The sender transmits the s \mathbb{F}_{q^ℓ} -vectors of lengths d_{M_i} :

$$L_{M_1} X G^1, \dots, L_{M_s} X G^s.$$

Let $j \in M_i$ for some $i \in [r]$. User j considers only r vectors, say these are:

$$L_{M_1} X G^1, \dots, L_{M_r} X G^r,$$

and by assumption can solve for some vectors $\mathbf{a}_i, \mathbf{c}_i$

$$R_j = \mathbf{c}_i L_{M_i} + \mathbf{a}_i V^{(j)}.$$

Thus j can recover

$$R_j X G^i = \mathbf{c}_i L_{M_i} X G^i + \mathbf{a}_i V^{(j)} X G^i$$

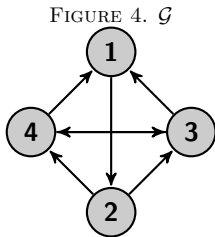
as User j knows $L_{M_i} X G^i$, $V^{(j)} X$ and G^i . So, we can compute

$$R_j X [G^1, \dots, G^r]$$

and from the MDS property it is possible to obtain $R_j X$. \square

REMARK 53. Theorem 52 generalizes the statement of [24, Theorem 2]. However, the scheme given in the proof of [25, Theorem 2] (this is the full version of [24]) to establish the upper bound, is incorrect. We assert that the statement of the theorem is still valid since it is special case of Theorem 52 and the parameters φ^p and φ_i^p generalize those given in [25]. We provide an example below to show that the scheme proposed in the proof of [25, Theorem 2] does not work.

Consider the instance of the ICSI problem with $m = n = 4$, $f(i) = i$ for all i and side information $\mathcal{X}_1 = \{2\}$, $\mathcal{X}_2 = \{3, 4\}$, $\mathcal{X}_3 = \{1, 4\}$ and $\mathcal{X}_4 = \{1, 3\}$. The graph \mathcal{G} associated with this instance is given in Figure 4. It can be checked that



$\varphi^p(\mathcal{G}) = 3$ and from the LP relaxation we obtain $\varphi_f^p(\mathcal{G}) = 5/2$. Consider for example the set $\mathcal{M}^{opt} = \{M_1 = \{1, 2, 3\}, M_2 = \{1, 2, 4\}, M_3 = \{3, 4\}\}$ arising from an optimal solution of the LP problem. Then $r = 2$ and our data matrix is

$$X = \begin{bmatrix} X_1^1 & X_1^2 \\ X_2^1 & X_2^2 \\ X_3^1 & X_3^2 \\ X_4^1 & X_4^2 \end{bmatrix}.$$

In [25] the authors give the following scheme for the fractional parameter (we report part of the text of Theorem 2 in [25]): “... the first constraint in the LP relaxation of (2) implies that every user is in exactly r multicast groups. Hence, every user packet consists of r sub-packets and each sub-packet is transmitted using the scalar scheme corresponding to one of the r multicast groups.”

For all i , denote by L_i the matrix associated to the scheme used to encode the message for the users contained in the set M_i . In particular, we can consider the following matrices

$$L_1 = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \end{bmatrix}, L_2 = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}, L_3 = \begin{bmatrix} 0 & 0 & 1 & 1 \end{bmatrix}.$$

Note that only the receivers contained in M_i are able to decode when L_i is used to encode.

Following the scheme given in [25], we do not need to combine the sub-packets X^1 and X^2 , using an MDS code, as in the proof of Theorem 52. Therefore, the message transmitted using this scheme will be of type

$$Y = (L_1 X^{i_1}, L_2 X^{i_2}, L_3 X^{i_3})$$

where $i_j \in \{1, 2\}$ for each j . Thus it should be possible to find a choice of the i_j 's such that all the receivers are able to retrieve the requested packet.

Suppose we choose $i_1 = 1, i_2 = 2$ and $i_3 = 1$. Note that in this case the receivers 1, 2 and 4 can retrieve their requested packets, but receiver 3 obtains only the first sub-packet. It can be checked that for all possible choice of i_j , there is at least one receiver

that obtains only one of its two requested sub-packets. On the other hand, using an \mathbb{F}_2 -[3, 2, 2] MDS code to combine the sub-packets, we can satisfy all the requests by sending:

$$Y = (L_1X^1, L_2X^2, L_3(X^1 + X^2)).$$

THEOREM 54. *There are achievable linear index codes corresponding to $\varphi_i^p(\mathcal{I})$ and $\varphi_{if}^p(\mathcal{I})$ implying $\beta(\mathcal{I}) \leq \varphi_{if}^p(\mathcal{I}) \leq \varphi_i^p(\mathcal{I})$.*

Proof. Fix a set of coding vectors $\{\mathbf{v}_C \in \mathcal{R}(C)\}$ for each $C \in \mathcal{C}$. Let $\mathcal{C}^{opt} = \{C_1, \dots, C_s\}$ be the set of cliques for which $y_C = 1$ in the optimal solution $(\{t_M : M \subset [m]\}, \{y_C : C \in \mathcal{C}\})$ of (6). Fix a multicast group M and let G be a generator matrix of an $[s, t_M]$ MDS code. Associate each i th column of G to the clique C_i in \mathcal{C}^{opt} . For this multicast group, the sender transmits

$$Y = \sum_{C_i \cap M \neq \emptyset} \mathbf{v}_{C_i} X G^i.$$

Given the side-information of User $j \in M$ this sum reduces to one involving only t_M cliques, which we may assume to be C_1, \dots, C_{t_M} , yielding

$$\sum_{i=1}^{t_M} \mathbf{v}_{C_i} X G^i = (\mathbf{v}_{C_1} X, \dots, \mathbf{v}_{C_{t_M}} X) [G^1, \dots, G^{t_M}],$$

and inverting the matrix $[G^1, \dots, G^{t_M}]$ we can recover $(\mathbf{v}_{C_1} X, \dots, \mathbf{v}_{C_{t_M}} X)$. As j is contained in one of these cliques it can decode $R_j X$.

Let us consider, now, the LP relaxation of (6). Let $(\{t_M, a_M : M \subset [m]\}, \{y_C : C \in \mathcal{C}\})$ be an optimal solution. Let r_1 denote the least common denominator of the y_C and the t_M and let r_2 denote the least common denominator of the a_M . Define $\hat{y}_C = r_1 y_C$, $\hat{t}_M = r_1 t_M$ and $\hat{a}_M = r_2 a_M$. Every clique C is assigned an integral weight in $[r_1]$ and every multicast group M is assigned an integral weight in $[r_2]$. Denote as before the multi-set of cliques by \mathcal{C}^{opt} and the multi-set of multicast groups by \mathcal{M}^{opt} . Every user is contained in r_1 cliques and in r_2 multicast groups. Moreover, every multicast group in which a user j lies intersects all the r_1 cliques related to j . We represent X as an $n \times r_1 r_2$ matrix over a subfield of \mathbb{F}_{q^t} . Let $s_1 = \sum_C \hat{y}_C$, $s_2 = \sum_M \hat{a}_M$ and let H be a generator matrix of an $[s_1 s_2, r_1 r_2]$ MDS code. We index each column of H by the pair (k, i) associated to a multicast group M_k and clique C_i .

Now fix a multicast group M_k and consider a matrix G related to an $[s_1, t_{M_k}]$ MDS code. The following vector is transmitted:

$$Y = \sum_{C_i \cap M_k \neq \emptyset} (\mathbf{v}_{C_i} X H^{(k,i)}) G^i.$$

Let $j \in M_k$. As before, we may assume that, using its side-information, j recovers

$$\sum_{i=1}^{t_{M_k}} (\mathbf{v}_{C_i} X H^{(k,i)}) G^i$$

From the MDS property of the code generated by G , j obtains

$$((\mathbf{v}_{C_1} X H^{(k,1)}), \dots, (\mathbf{v}_{C_{t_{M_k}}} X H^{(k,t_{M_k})})).$$

Restricting to the cliques that contain j we obtain

$$(\mathbf{v}_{C_1} X H^{(k,1)}, \dots, \mathbf{v}_{C_{r_1}} X H^{(k,r_1)}).$$

As j is in r_2 multicast groups, without loss of generality j recovers

$$(\mathbf{v}_{C_1} X H^{(1,1)}, \dots, \mathbf{v}_{C_{r_1}} X H^{(1,r_1)}, \dots, \mathbf{v}_{C_1} X H^{(r_2,1)}, \dots, (\mathbf{v}_{C_{r_1}} X H^{(r_2, r_1)}).$$

Now using the side information j can compute $R_j X \tilde{H}$ where

$$\tilde{H} = [H^{(1,1)}, \dots, H^{(1,r_1)}, \dots, H^{(r_2,1)}, \dots, H^{(r_2,r_1)}].$$

From the MDS property of H , the receiver j obtains $R_j X$ and hence, φ_{if}^p is achievable. \square

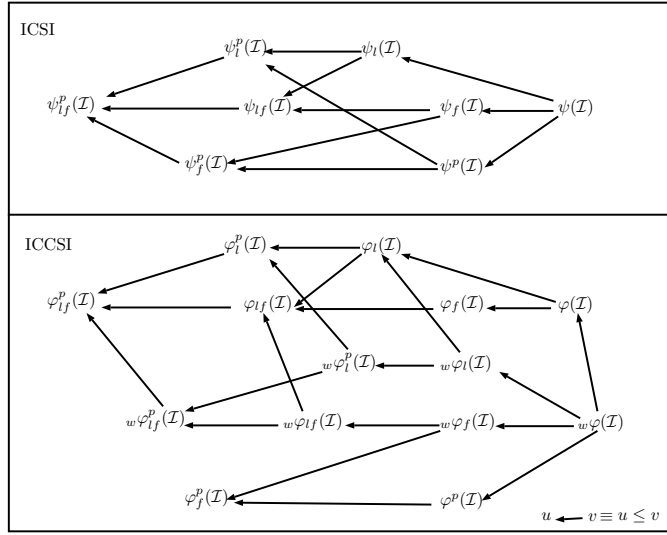


FIGURE 5. The bottom part of the figure describes ICCSI bounds introduced in this work while the top describes the ICSI case. Smaller quantities are placed to the left and the weakest bound is placed to the rightmost of the figure. Arrows indicate the relationship they satisfy.

REMARK 55. The parameters φ^p and φ_l^p are not comparable. From the parameters given in [24] we have that there exist instances of the ICSI problem for which $\varphi^p(\mathcal{I}) \geq \varphi_l^p(\mathcal{I})$. Now consider the ICCSI instance with $m = n = 3$, $q = 2$, $\mathcal{X}^{(S)} = \mathbb{F}_2^3$.

$$V^{(1)} = [0 \ 1 \ 1] \quad V^{(2)} = [1 \ 1 \ 1] \quad V^{(3)} = [1 \ 1 \ 1],$$

and $R_1 = 100$, $R_2 = 010$, $R_3 = 001$.

In order to satisfy the requests of a receiver using only one vector then the coding vectors should be

- $\mathbf{v}_1 = 100$ or $\mathbf{v}'_1 = 111$ for User 1;
- $\mathbf{v}_2 = 010$ or $\mathbf{v}'_2 = 101$ for User 2;
- $\mathbf{v}_3 = 001$ or $\mathbf{v}'_3 = 110$ for User 3.

Then the set of all cliques is $\mathcal{C} = \{\{1\}, \{2\}, \{3\}\}$. Moreover we can see that $\mathbf{v}_i, \mathbf{v}'_i \notin \mathcal{X}^{(1)}$ for all i . Now if we consider the multicast group $M = \{1, 2, 3\}$ we can note that $d_M = 2$ and that $t_M = 3$ because none of the six vectors above is in the space $\mathcal{X}^{(1)}$. Then we have $2 = \varphi^p(\mathcal{I}) \leq \varphi_l^p(\mathcal{I}) = 3$.

REMARK 56. The parameters φ^p and φ are not comparable. From the parameters given in [24], there exist instances of the ICSI problem for which $\varphi(\mathcal{I}) \geq \varphi^p(\mathcal{I})$. Now consider the ICCSI instance with $m = n = 2$, $q = 2$, $\mathcal{X}^{(S)} = \mathbb{F}_2^2$.

$$V^{(1)} = [1 \ 1] \quad V^{(2)} = [0 \ 0],$$

and $R_1 = 10$, $R_2 = 01$. It is easy to check that using the multicast group partition we need two transmissions, but it can be seen that $\{1, 2\}$ is a clique and that $\mathbf{v}_{\{1,2\}} = 01 \in \mathcal{R}(\{1, 2\})$, yielding $1 = \varphi(\mathcal{I}) \leq \varphi^p(\mathcal{I}) = 2$.

REMARK 57. We have $\varphi_l^p(\mathcal{I}) \leq \varphi_l(\mathcal{I}) \leq \varphi(\mathcal{I})$. It is easy to check that $\varphi_l(\mathcal{I}) \leq \varphi(\mathcal{I})$ as t is at most equal to the number of cliques that form a partition of $[m]$. Then we have also $\varphi_l^p(\mathcal{I}) \leq \varphi_l(\mathcal{I})$. In fact, among the possible optimal solution to obtain we have those where $M = [m]$ and in that case we obtain exactly $\varphi_l(\mathcal{I})$.

REMARK 58. It is possible to introduce a weak definition of clique. $C \subseteq [m]$ is called weak clique if for all $i, j \in C$ we have $R_j \in \mathcal{X}^{(i)}$ or $\langle R_j \rangle = \langle R_i \rangle$. Using this definition, it is possible to introduce the notion of a weak clique cover, a local weak clique cover and a partitioned local weak clique cover with respective corresponding parameters ${}_w\varphi(\mathcal{I})$, ${}_w\varphi_l(\mathcal{I})$ and ${}_w\varphi_l^p(\mathcal{I})$ along with their fractional counterparts.

REMARK 59. If C is a weak clique then it is also a generalized clique. We can encode the message using the sum of distinct requests as vector \mathbf{v}_C . Moreover from the definition of weak clique, if we consider a clique as a multicast group M then it results $d_M = 1$. Therefore $\varphi^p(\mathcal{I}) \leq {}_w\varphi(\mathcal{I})$ and the same holds for the fractional parameters. However also in this case the partitioned local weak clique cover and the partitioned multicast cover are not comparable (see example in Remark 55).

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