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Three-dimensional speckle size in generalized optical systems with limiting apertures

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Correlation properties of speckle fields at the output of quadratic phase systems with hard square and circular apertures are examined. Using the linear canonical transform and ABCD ray matrix techniques to describe these general optical systems, we first derive analytical formulas for determining axial and lateral speckle sizes. Then using a numerical technique, we extend the analysis so that the correlation properties of nonaxial speckles can also be considered. Using some simple optical systems as examples, we demonstrate how this approach may be conveniently applied. The results of this analysis apply broadly both to the design of metrology systems and to speckle control schemes. © 2009 Optical Society of America

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1. INTRODUCTION

Coherent laser light reflected from an optically rough surface produces a grainy interference pattern known as speckle. For a given illumination wavelength and optical system, this speckle pattern is dependent on the profile of the rough surface. Measuring variations in the speckle field (for example, by capturing a series of sequential images) the user has a noncontact means of monitoring surface changes as external forces and stresses are applied [1–6]. Speckle size plays a role in determining the resolution and dynamic range of such metrology systems, and the ability to predict and control speckle size can thus be used to improve system performance. In speckle photography systems, for example, it can be used to match the speckle and camera pixel sizes, while for speckle interferometry it is preferable to have many speckles per camera pixel [7]. In other optical applications such as digital holography, speckle is treated as a source of noise, and insight into speckle correlation properties may aid in the development of speckle reduction techniques [8]. It is known that speckle size depends on the lenses, apertures, and sections of free space in an optical system. It is also dependent on the wavelength used and, although not discussed here, polarization diversity [8]. In this paper, simple formulas are presented to estimate the lateral and on-axis longitudinal speckle size (for input circular and square hard apertures) at the output of quadratic phase systems described using the linear canonical transform (LCT) and the corresponding ray-tracing ABCD matrices [9–11]. The analysis is then extended so that the off-axis speckle sizes can also be determined in a straightforward manner, using a set of simple analytical functions.

Lateral speckle size was first investigated by Goldfisher [12] by examining the width of the autocorrelation function of a free space speckle pattern. Later, Leushacke and Kirchner [13] derived expressions for the average speckle width and length following free space (Fresnel) propagation from both circular and square apertures. On-axis speckle size in general ABCD systems with soft Gaussian apodized apertures has been discussed by Yura et al. [14]. We have previously determined speckle size numerically in ABCD systems for a 1-D rectangular slit [15]; however, these results are somewhat awkward to apply. This paper makes the following additional contributions: (i) The previous analysis [15] is extended to include square and circular apertures; (ii) a set of compact analytical equations that allow straightforward estimation of the lateral and on- and off-axis longitudinal speckle size for any general ABCD system is derived, and a simple technique to apply these formulas to system specific solutions is provided; and (iii) some standard optical systems are examined to demonstrate the effectiveness of the resulting approach.

The layout of the paper is as follows: In Section 2 we briefly introduce the LCT and use this transform to describe a speckle field at the output of a general paraxial optical system. This speckle field deforms as optical elements within the bulk optical system are moved or changed. Using correlation techniques we derive a function that provides a measure of the similarity between speckle fields originating from the same input field but propagating through two different LCT systems. We refer to this measure as the mutual correlation coefficient (of intensity) and use it to define speckle size. In Section 3, special cases of the mutual correlation coefficient are examined individually for different input aperture shapes. In Subsection 3.A an expression for the first minimum of the mutual correlation coefficient for 1-D square apertures in generalized ABCD systems is derived and is used to define our lateral and on-axis longitudinal speckle
sizes. Subsection 3.B provides a similar analysis for the circular aperture case. In Section 4 the analyses are extended to longitudinal speckle observed off-axis. In Section 5 some commonly used optical systems are examined. Speckle size is calculated for these systems, primarily using the first minimum definition derived in this paper but also using the full-width half-maximum definition sometimes used in the literature [8,11] for the circular aperture case. Finally, in the conclusion in Section 6, a discussion of the main results is presented.

2. ABCD RAY MATRICES AND THE CORRELATION COEFFICIENT OF INTENSITY

A. Integral Transforms and the ABCD Ray Matrix Notation

Within paraxial scalar diffraction theory, light propagation can be described using the Fresnel transform (FST) and the effect of a thin lens by a chirp transform. All such integral transforms are special cases of the LCT, a three-parameter class of integral transforms that is typically defined in terms of the parameters A, B, and D [5,9–11]. By choosing appropriate values of these parameters, the effect of successive chirp and propagation transforms can be described using the Collins or ABCD matrix techniques [9]. The advantage of retaining these A, B, and D parameters throughout a derivation is that the resulting solutions will be applicable to any paraxial quadratic phase system (QPS). In Eq. (1) we define the two-dimensional LCT,

\[ u(x,y) = \text{LCT}(u(x_0,y_0))(x,y) \]

\[ \frac{1}{j\lambda B} \int_{-\infty}^{\infty} u(x_0,y_0)p(x_0,y_0) \]

\[ \times \exp \left[ \frac{j\pi}{\lambda B} (D x^2 - 2xx_0 + A x_0^2) \right] \]

\[ \times \exp \left[ \frac{j\pi}{\lambda B} (D y^2 - 2yy_0 + A y_0^2) \right] \, dx_0 dy_0, \quad (1) \]

where \( p(x_0,y_0) \) is the pupil function in the input plane. The 2-D LCT in Eq. (1) describes the mapping of a field \( u(x_0,y_0) \), at an optically rough surface, to the field \( u(x,y) \) at the output of the LCT system. Equation (2) gives the \([A,B],[C,D] \) values in Collins's matrix form [9] for the following: Eq. (2a), propagation through a section of free space or FST; Eq. (2b), a thin lens or chirp modulation; and Eq. (2c), a Fourier transform (FT):

\[ \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, \quad (2a) \]

\[ \begin{bmatrix} 1 & z \\ 0 & 1 \end{bmatrix}, \quad (2b) \]

\[ \begin{bmatrix} 1 & z \\ -1 / f & 1 \end{bmatrix}, \quad (2c) \]

where \( z \) is the propagation distance, \( f \) is the focal length of a convex lens, and the matrices in all the cases we consider have the property \( AD - BC = 1 \). Matrices that describe a combination of the above operations can be constructed by a simple concatenation of the appropriate matrices [5].

B. Mutual Correlation Coefficient of Intensity, \( \mu_I \)

The mutual correlation coefficient of intensity provides a means of comparing the similarity between two fields. It is sometimes referred to in the literature as “the normalised autocorrelation function of intensity” [16], or as “co-variance” [6,14], but in all cases represents a normalized form of the correlation between two intensity fields that result from the same input field. The correlation between the light intensity distributions, \( I(x) = \lvert u(x) \rvert^2 \), is given by

\[ R(x,\bar{x}) = \langle I(x) I(\bar{x}) \rangle / \langle I(x) \rangle \langle I(\bar{x}) \rangle \]

\[ = \langle J_A(x) J_A(\bar{x}) \rangle + |J_A(x) J_A(\bar{x})|^2, \quad (3) \]

where \( J_A(x) J_A(\bar{x}) \) is the mutual field amplitude between two Gaussian, statistically independent fields [8,16], captured in different LCT domains and laterally displaced at the output by \( \bar{x} - x \),

\[ J_A(x,\bar{x}) = (u_{ABCD}(x) u^*_{ABCD}(\bar{x})) \]

where \( \langle \rangle \) denotes ensemble average and subscript * denotes complex conjugation. For notational simplicity in the following expressions, we perform a 1-D analysis. In Section 3 we examine both square and circular apertures and extend the analysis to the 2-D case with appropriate substitutions of variables. Using the 1-D form of Eq. (1), the correlation between two displaced fields in Eq. (4) is given by

\[ \left\langle \frac{1}{j\lambda B_1 B_2} \int_{-\infty}^{\infty} p^2(x_0) u(x_0) u^*(\bar{x}_0) \right. \]

\[ \times \exp \left[ \frac{j\pi}{\lambda B_1} (D x^2 - 2xx_0 + A x_0^2) \right] \]

\[ \times \exp \left[ -j\pi \lambda B_2 (D \bar{x}_0^2 - 2\bar{x}_0 x_0 + A \bar{x}_0^2) \right] \, dx_0 d\bar{x}_0 \right. \]

where the pupil function \( p(x_0) \) is assumed to be a real-valued, hard-edged aperture at the input plane. We now make two simplifying assumptions about the statistics of the speckle; (i) the speckle field is fully developed and is delta correlated at the rough surface, i.e., \( \langle u(x_0) u^*(\bar{x}_0) \rangle = C \delta(x_0 - \bar{x}_0) \), where \( C \) is a constant; and (ii) the intensity fields \( I(x) \) and \( I(\bar{x}) \) are slowly changing and approximately equal to each other [8]. Thus a study of \( J_A(x,\bar{x},z,\bar{z}) \) is sufficient to describe the decorrelation of the speckle field and so the speckle size [13]. We note that if assumption (i) is not satisfied, the following equations are valid only in the far field of the aperture [8] Chap. 4.
Using these assumptions, Eq. (5) can be rewritten as

\[
C \exp \left[ j \frac{\pi}{\lambda} \left\{ \frac{D_1}{B_1} x^2 - \frac{D_2}{B_2} \right\} \right] \int_{-\infty}^{\infty} p^2(x_0) \\
\times \exp \left\{ j \frac{\pi}{\lambda} \left[ \left( \frac{\bar{x}}{B_2} - \frac{x}{B_1} \right) 2x_0 + \left( \frac{A_1}{B_1} - \frac{A_2}{B_2} \right) x_0^2 \right] \right\} dx_0.
\]


The mutual correlation coefficient (of intensity) is equal to the absolute value squared of the normalized mutual field amplitude,

\[
\mu_I(x, \bar{x}, ABCD_1, ABCD_2) = \left| \frac{J_A(x, \bar{x}, ABCD_1, ABCD_2)}{\sqrt{J_A(x, \bar{x}, ABCD_1, ABCD_1) J_A(\bar{x}, \bar{x}, ABCD_2, ABCD_2)}} \right|^2.
\]

Substituting Eq. (6) into Eq. (7) gives

\[
\left\{ \int_{-\infty}^{\infty} p^2(x_0) \exp[j(\alpha x_0 + \pi x_0^2)] dx_0 \right\}^2 = \left\{ \int_{-\infty}^{\infty} p^2(x_0) dx_0 \right\}^2,
\]

where

\[
\alpha = \frac{2\pi}{\lambda} \left( \frac{\bar{x}}{B_2} - \frac{x}{B_1} \right), \quad \tau = \frac{\pi}{\lambda} \left( \frac{A_1}{B_1} - \frac{A_2}{B_2} \right).
\]

Equation (8) is the general form of the mutual correlation coefficient used in this paper to derive speckle size for 1-D square aperture systems.

3. LATERAL AND ON-AXIS LONGITUDINAL SPECKLE SIZE

The speckle size for two special and important cases, lateral and on-axis longitudinal speckles, are now derived. The term lateral refers to speckle width perpendicular to the optical axis, while longitudinal speckle collectively describes speckle length coincident (on-axis) and noncoincident (off-axis) with the optical axis. Mathematical definitions of lateral and longitudinal speckles are used, which allows analytical solutions of Eq. (8) to be found for both aperture types. For lateral speckle we assume that the bulk optical LCT system remains physically unchanged, i.e., \( ABCD_1 = ABCD_2 \); thus \( \tau = 0 \), and Eq. (8) is simplified accordingly. This corresponds to performing an autocorrelation of the speckle intensity pattern and noting the width of the resulting autocorrelation peak. Finding the lateral speckle size thus involves answering the question, how far must we displace the speckle pattern laterally before the first minimum of correlation occurs? In deriving longitudinal speckle size, we examine the decorrelation between two speckle fields produced from the same input field as the \( ABCD \) system parameters are varied. For the longitudinal case, \( ABCD_1 \neq ABCD_2 \), however, the output planes are assumed laterally stationary, e.g., \( x = \bar{x} \). Furthermore, for on-axis longitudinal speckle, \( x = \bar{x} = 0 \). However this simplification will not be made until the end of the derivations so that off-axis solutions to the mutual correlation coefficient can be explored. The analysis is first performed for 1-D input square solutions and then for 2-D circular apertures.

A. Speckle Size for Square Apertures

The 1-D real-valued pupil function for a hard-edged square aperture is

\[
p(x_0) = \begin{cases} 
1 & |x_0| \leq L/2 \\
0, & \text{otherwise} 
\end{cases},
\]

where \( L \) is the width of the aperture. The full 2-D solution for the square aperture case involves only a multiplication of the two orthogonal 1-D solutions. Equation (8) now becomes

\[
\mu_I(x, \bar{x}, ABCD_1, ABCD_2) = \left| \frac{1}{L} \int_{-L/2}^{L/2} \exp[j(\alpha x_0 + \pi x_0^2)] dx_0 \right|^2.
\]

1. Lateral Speckle Size

Lateral speckle size (speckle width) is defined by the maximum lateral displacement, \( x = \bar{x} \), that can take place before the first minimum of \( \mu_I \) is reached. Since only an autocorrelation of the field must be considered, \( ABCD_1 = ABCD_2 \) and \( \tau = 0 \). Simplifying Eq. (10) gives

\[
\mu_I(x, \bar{x}) = \left| \frac{1}{L} \int_{-L/2}^{L/2} \exp[j(\alpha x_0 + \pi x_0^2)] dx_0 \right|^2 = \frac{2 \sin^2 \left( \frac{L\alpha}{2} \right)}{L\alpha}.
\]

The minima of Eq. (11) are located at the points at which \( \sin(L\alpha/2) = 0 \), i.e., when \( L\alpha/2 = N\pi \), where \( N \) is an odd natural number. The first minimum of the correlation coefficient of intensity occurs when \( N = 1 \), giving

\[
L = \frac{2\pi}{\lambda B} (\bar{x} - x) = \pi.
\]

Thus speckle width, \( \epsilon_x \), is defined as

\[
\epsilon_x = \bar{x} - x = \lambda B/L.
\]

Equation (13) is the general form for speckle width when a square aperture is at the input plane of the system, and \( B \) is dependent on the specific parameters of the optical system.

2. Longitudinal Speckle Size

Longitudinal speckle size is defined by the maximum change to the optical system that can take place before the first minimum of \( \mu_I \) is reached. The lateral position remains unchanged for this case; consequently, \( \bar{x} = x \) and \( \mu_I \) is no longer a function of lateral displacement. In order to find an analytical solution to Eq. (10), we apply a change of variable, \( t = x_0 \sqrt{2\pi/\pi} + \alpha/\sqrt{2\pi} \), giving
Introducing the Fresnel integrals, $C(z)$ and $S(z)$ [13,18], Eq. (14) can be written as
\begin{equation}
\left[ \frac{1}{2b} \exp \left[ -j \frac{m^2 a^2}{2} \right] [C(a+b) - C(a-b) + jS(a+b) - jS(a-b)] \right]^2,
\end{equation}
where $a = a/\sqrt{2\pi}$ and $b = L/\sqrt{2\pi}$. This simplifies to
\begin{equation}
\frac{1}{2b^2}[(C(a+b) - C(a-b))^2 + (S(a+b) - S(a-b))^2].
\end{equation}

Equation (16) is the general analytical form of $\mu_f(ABCD_1,ABCD_2)$ for longitudinal speckle in a 1-D square aperture system.

For the special case of on-axis speckle, $x=0 \Rightarrow a=0$, and Eq. (16) can be written as
\begin{equation}
\frac{C^2(b) + S^2(b)}{|b|^2},
\end{equation}
since $C(-b) = -C(b)$ and $S(-b) = -S(b)$. The first minimum of Eq. (17) occurs at $b_{\text{min}} = 1.9115$. Substituting for $b$ gives $L/\sqrt{2\pi} = 1.9115$. Therefore, the first minimum of the mutual correlation coefficient for on-axis longitudinal speckle occurs when
\begin{equation}
A_1 \frac{A_2}{B_2} = \frac{7.31\lambda}{L^2}.
\end{equation}
On-axis speckle length is determined from Eq. (18) by substituting in system-specific values of $A_1$, $A_2$, $B_1$, and $B_2$. The application of Eq. (18) to some well-known optical systems is discussed in Section 5.

B. Speckle Size for Circular Apertures
In this case the 2-D pupil function is given by
\begin{equation}
p(r_0) = \begin{cases} 1, & |r_0| \leq D_0/2 \\ 0, & \text{otherwise} \end{cases},
\end{equation}
where $D_0$ is the aperture diameter. The 2-D equivalent of the mutual correlation coefficient is
\begin{equation}
\mu_f(x,\tilde{x},y,\tilde{y},ABCD_1,ABCD_2) = \left| \int_0^\infty \int_0^\infty p^2(x_0,y_0) \exp[j((a_x x_0 + a_y y_0) + \pi(x_0^2 + y_0^2))] dx_0 dy_0 \right|^2,
\end{equation}
where
\begin{align*}
\alpha_x &= \frac{2\pi}{\lambda} \left( \frac{\tilde{x} - x}{B_2 - B_1} \right), \\
\alpha_y &= \frac{2\pi}{\lambda} \left( \frac{\tilde{y} - y}{B_2 - B_1} \right).
\end{align*}
Transforming to cylindrical coordinates, $x_0 = r_0 \cos \theta$, $y_0 = r_0 \sin \theta$, $a_x = \Omega \cos \phi$, and $a_y = \Omega \sin \phi$, where
\begin{align*}
\Omega &= \sqrt{\alpha_x^2 + \alpha_y^2} = \frac{2\pi}{\lambda} \left( \frac{\tilde{r}}{B_2 - B_1} \right), \\
r_0 &= \sqrt{x_0^2 + y_0^2}.
\end{align*}
Eq. (20) becomes
\begin{equation}
\mu_f(r,\tilde{r},ABCD_1,ABCD_2) = \left| \int_0^{2\pi} \int_0^r p^2(r_0) \exp[j(\Omega r_0 \cos \theta \cos \phi + \sin \theta \sin \phi + \pi r_0^2)] r_0 \, dr_0 \, d\theta \right|^2.
\end{equation}
Employing trigonometric identities and changing the limits based on the definition of the pupil function, Eq. (21) becomes

\[
\left| \int_0^{D_0/2} \int_0^{2\pi} \exp[j\Omega_0 \cos(\theta - \phi)] \exp[j \pi \frac{\alpha}{4} r_0 d\theta r_0] \right|^2.
\]

(22)

Performing the integral in the denominator and normalizing the radial coordinate, i.e., \( r_N = 2r_0 / D_0 \), Eq. (22) becomes

\[
\left| \frac{1}{\pi} \int_0^{1} \int_0^{2\pi} \exp\left[ j \frac{\Omega D_0 r_N}{2} \cos(\theta - \phi) \right] \right|^2 \times \exp\left[ j \frac{\pi}{4} r_N d\theta r_N \right]
\]

\[
= \left| \int_0^{1} J_0(q r_N) \exp[j \pi \frac{\alpha}{4} r_N d\theta r_N \right|^2,
\]

(23)

where \( p = \pi D_0 / 4 \), \( p = \Omega D_0 / 2 \), and \( J_0(x) \) is the zero-order Bessel function [17]. The integral in Eq. (23) is the Fourier–Bessel or Hankel transform.

1. Lateral Speckle Size

Since only an autocorrelation needs to be considered, \( ABCD_1 = ABCD_2 \) and \( p = \pi = 0 \). Equation (23) for lateral speckle is written as

\[
\mu_l(r, \bar{r}) = \left| 2 \int_0^{1} J_0(q r_N) r_N d\theta r_N \right|^2 = \frac{2 J_1(q)}{q}.
\]

(24)

which is the Airy function [17]. The first minimum of this function occurs at \( q_{\text{min}} = 3.832 \), and since \( B_1 = B_2 \),

\[
\frac{D_0 \pi}{\lambda B} (\bar{r} - r) = 3.382.
\]

(25)

Therefore the speckle width \( \epsilon_r \) is

\[
\epsilon_r = \bar{r} - r = 1.22 \lambda B / D_0.
\]

(26)

2. Longitudinal Speckle Size

As before, longitudinal speckle size is defined by the maximum change to the optical system that can take place before maximum decorrelation occurs. In this case, \( \bar{r} = r \) and Eq. (23) is in the form of Eq. (20) in [18]. Therefore

\[
\mu_l(ABCD_1, ABCD_2) = 2 \exp\left[ \frac{4p}{2} \right] \sqrt{\frac{\pi}{\pi \sum_{p = 0}^{\infty} (2n + 1)}} \times (-j)^n J_{n+1/2}(p) J_{2n+1}(q) / q,
\]

(27)

For the case of on-axis speckle, \( r = 0 \Rightarrow q = 0 \); furthermore, since

\[
\lim_{q \rightarrow 0} \left[ \frac{J_{2n+1}(q)}{q} \right] = \begin{cases} \frac{1}{2}, & n = 0 \\ 0, & n > 0 \end{cases}.
\]

(28)

Eq. (27) becomes [19]

\[
\left| \sqrt{\frac{\pi}{p}} J_{1/2}(p) \right|^2 = \sin\left( \frac{p}{2} \right) / p.
\]

(29)

The first minimum of this function occurs when \( p_{\text{min}} / 2 = \pi \). Backsubstituting for \( p \) gives the equation from which the system specific definition of axial speckle size at the output plane can be extracted,

\[
\frac{A_1}{B_1} - \frac{A_2}{B_2} = 8\lambda / D_0^2.
\]

(30)

The application of Eq. (30) is discussed in Section 5.

4. OFF-AXIS LONGITUDINAL SPECKLE SIZE

The analysis in Section 3 provides two closed-form equations to estimate longitudinal speckle length. However these formulas are valid only for speckle observed on the principal axis. Off-axis speckles are those observed in any part of the output plane that is noncoincident with the optical axis. Although the difference in size between on- and off-axis speckles is small close to the optical axis [8], speckle length drops off after this central “plateau.”

The analytical solutions for speckle size presented in Section 3 were derived for the special cases of \( a = 0 \) (on-axis speckle with a square aperture) and \( q = 0 \) (on-axis speckle with a circular aperture). Without these simplifications, it is not, to our knowledge, possible to extend the simple analytical formulation to the off-axis case. It is however possible to numerically determine the relationship between \( a \) and \( b \) (or \( p \) and \( q \)) at the first minimum of \( \mu_l(ABCD_1, ABCD_2) \). We proceed, following [15], by identifying numerically a “boundary of correlation” (BOC) curve on a contour plot of \( \mu_l(ABCD_1, ABCD_2) \). The points on this curve represent the first minima of \( \mu_l(ABCD_1, ABCD_2) \) for all possible values of \( a \) and \( b \) (or \( p \) and \( q \)). We proceed by fitting analytical functions to these BOC points to provide the user with equations that can be used to determine off-axis speckle size for apertured \( ABCD \) systems. We also include a “half-maximum” line in the contour plot to mark where \( \mu_l(ABCD_1, ABCD_2) = 0.5 \) for the circular aperture case. Twice the distance of this curve from the origin is sometimes used in the literature to estimate speckle size [8,14,20]. We note that the half-maximum definition of speckle always predicts a smaller size than the corresponding first-minimum prediction [13]. We have also observed that when using the half-maximum definition, the off-axis decorrelation characteristics appear to be consistently underestimated for the longitudinal case.

A. Square Aperture

For the square aperture case, it is easier to first determine the BOC of \( \mu_l(ABCD_1, ABCD_2) \) parameterized in terms of \( a \) and \( \tau \), as shown in [15]. This is because the first minima of \( \mu_l(ABCD_1, ABCD_2) \) are sharper and thus more easily located numerically when the function is pa-
In the BOC curve in the positive quadrant of Fig. 1, a relatively flat segment of the BOC is observed, followed by a longer curve of negative curvature. Given the symmetry of the BOC, the curves corresponding to negative \(a\) or \(b\) values can be related to those in the positive quadrant by a simple change of sign. In Fig. 2, where the different segments of the BOC are identified more clearly, a slight positive inflection in the flat portion of the BOC is observed. We therefore give the option of classifying this segment either as a straight line, “Line 1,” or, if a more accurate representation is required, as the combination of two shallow curves, “Curve 1(a)” and “Curve 1(b).” The longer segment of negative curvature will be referred to as “Curve 2.” We note that Curve 2 has been extended to provide values in the region of the discontinuity, i.e., where the minima could not be unambiguously identified. In Table 1, the equations describing each of these curve fits, the range of \(a\) values over which each fit is valid, and the mean square error between the data and the fits [21] are given.

In order to solve the equations in Table 1, it is necessary to write them as a function of a single variable. From our definitions, \(a\) and \(b\) written in terms of the \(ABCD\) parameters are

\[
a = \frac{x}{\sqrt{2/(\lambda B_1 B_2)(B_1 - B_2)}}, \quad \text{(31a)}
\]

\[
b = L \sqrt{\frac{1}{2x} \left( \frac{A_1}{B_1} - \frac{A_2}{B_2} \right)}. \quad \text{(31b)}
\]

By dividing Eq. (31b) by Eq. (31a) it is possible to rewrite \(b\) in terms of \(a\) alone and solved. While a different \(a\) value will result from each equation, the acceptable \(a\) value is the one that lies within the range specified for that equation. By substituting the resulting value of \(a\) into Eq. (31a), the off-axis speckle size can be calculated.

Special cases of \(a\) and \(b\) for two simple optical systems are provided in Table 2. In the examples that are provided, \(\Delta z\) refers to an output plane normal displacement and will provide a result equivalent to the longitudinal speckle size, \(\epsilon_z\), when the \(a\) or \(b\) values that result from these equations lie on the BOC. In order to simplify the expressions in Table 2, the assumption that \(z \gg \Delta z\) was made. Thus for the Fresnel case shown in Fig. 3(a), \(z(z + \Delta z) \equiv z^2\), and for the single-lens case in Fig. 3(b),

![Fig. 1. Contour plot of \(\mu_1(ABCD_1,ABCD_2)\) for the square aperture case, where the BOC marks the location of the first minima parameterized in terms of \(a\) and \(b\).](image)

![Fig. 2. (Color online) Plot of the BOC for the square aperture case, showing the range of \(a\) values for which each segment of the BOC curve is valid.](image)

![Table 1. Equations Describing the Fits to the Various Segments of the BOC, with the Associated Ranges and Mean-Square-Error Values](table)

<table>
<thead>
<tr>
<th>Square Aperture</th>
<th>Equation: (b(a))</th>
<th>Valid Ranges of (a)</th>
<th>Mean Square Error [21]</th>
</tr>
</thead>
<tbody>
<tr>
<td>Curve 1</td>
<td>1.911</td>
<td>(0 \leq a \leq 0.337)</td>
<td>(2.814 \times 10^{-4})</td>
</tr>
<tr>
<td>Curve 1(a)</td>
<td>(1.907 + 0.004 \exp(43.748a^{1.603}))</td>
<td>(0 \leq a \leq 0.163)</td>
<td>(5.173 \times 10^{-9})</td>
</tr>
<tr>
<td>Curve 1(b)</td>
<td>(1.954 \exp(-0.261a^{2.203}))</td>
<td>(0.163 \leq a \leq 0.337)</td>
<td>(7.073 \times 10^{-10})</td>
</tr>
<tr>
<td>Curve 2</td>
<td>(0.086 + 3.533 \exp(-1.448a^{0.557}))</td>
<td>(0.337 \leq a \leq \infty)</td>
<td>(1.409 \times 10^{-4})</td>
</tr>
</tbody>
</table>
In Section 5, the procedure used to calculate off-axis speckle size for these systems is applied.

B. Circular Aperture

The contour plot of \( \mu_1(ABCD_1,ABCD_2) \), parameterized as a function of \( p \) and \( q \), is shown in Fig. 4. Using numerical fitting techniques, equations for the three segments of the BOC curve and the half-maximum curve highlighted in Fig. 5 were determined. The equations for the three segments provide the relationship between \( p \) and \( q \) at the first minima of \( \mu_1(ABCD_1,ABCD_2) \) for the ranges and with the accuracies shown. A difficulty arises in identifying minima in the range \( 5.1 \leq p \leq 6.55 \). Following detailed numerical examination, we have found that in this range no sharply defined first minima exist. This introduces an ambiguity regarding the location of the BOC that can be observed graphically by noting the dashed lines in Fig. 5 or the minima that lie parallel to the contours of \( \mu_1(ABCD_1,ABCD_2) \) in Fig. 4. To overcome this ambiguity, we define a straight line to approximate the BOC in this region, going from the minimum \( q \) value of Curve 1 to the minimum \( p \) value of Curve 2. We refer to this line as the effective BOC line. Table 3 lists the equation describing each curve, the range of \( p \) values, and the accuracy of each fit. For completeness, curve fits to the half-maximum contour line are also given. From our definitions, the general expressions for \( p \) and \( q \) in terms of the \( ABCD \) parameters are

\[
p = \frac{D_0^2 \pi}{4\lambda} \left( \frac{A_2 - A_1}{B_2 - B_1} \right),
\]

\[(32a)\]

\[fz_2 \approx f(z_2 + \Delta z).\]
ing this value of within the range specified for that equation. By substituting systems are provided in Table 4. In Section 5, our procedures are applied to analyze these systems assuming input circular apertures.

5. EXAMPLES OF SOME WELL-KNOWN OPTICAL SYSTEMS

Two specific optical configurations are examined: a free space configuration, Fig. 3(a) and a single-lens system, Fig. 3(b). We determine the lateral and on-axis longitudinal speckle size for both cases and examine the change in longitudinal speckle size for a given offset from the optical axis. We note that although only the effect of changing the position of the output plane is examined, the analysis presented is sufficiently general so as to allow one to determine the correlation properties of a speckle system in which any paraxial system component value, i.e., ABCD parameter, is changed.

A. Free-Space Propagation (FST)

From Eq. (2), the ABCD parameters that describe Fig. 3(a) before the off-axis longitudinal speckle size for speckles observed off-axis. We use the same system component values as above but now consider as a function of only and solved numerically. The value resulting from Curve 2 is 0.541, which is within the range specified for that equation. By substituting this value of p into Eq. (32a), off-axis speckle size can be found.

Table 4. p and q Values for Some Commonly Used Optical Systems That Are Laterally Stationary

<table>
<thead>
<tr>
<th>Circular Aperture</th>
<th>p</th>
<th>q</th>
<th>q/p</th>
<th>ϵz</th>
</tr>
</thead>
<tbody>
<tr>
<td>FST system</td>
<td>D02πΔz(1/z2)</td>
<td>D0πrΔz(1/z2)</td>
<td>4r/D0</td>
<td>4πmaxλ [z/L]2</td>
</tr>
<tr>
<td>Single lens system</td>
<td>D02πΔz</td>
<td>D0fπr(z1−f)Δz</td>
<td>4r(z1−f)/D0f</td>
<td>4πmaxλ [f(z1+z2)−z1z2]/D0f</td>
</tr>
</tbody>
</table>

Note: Δz = z − Δz.

A. Free-Space Propagation (FST)

From Eq. (2), the ABCD parameters that describe the Fresnel-transforming systems shown in Fig. 3(a) before displacement of the output plane are ABCD1 = Eq. (2a), and the following displacement,

To extract speckle size information using the functions in Fig. 3(b). We determine the lateral and on-axis longitudinal speckle size for a given offset from the optical axis. We note that although only the effect of changing the position of the output plane is examined, the analysis presented is sufficiently general so as to allow one to determine the correlation properties of a speckle system in which any paraxial system component value, i.e., ABCD parameter, is changed.

A. Free-Space Propagation (FST)

From Eq. (2), the ABCD parameters that describe the Fresnel-transforming systems shown in Fig. 3(a) before displacement of the output plane are ABCD1 = Eq. (2a), and the following displacement,
specified range, i.e., 0.390 ≤ a ≤ ∞. Substituting into a = −e√2Δz/λx² from Table 2 allows us to solve for Δz at the point of decorrelation. In this case the off-axis longitudinal speckle size is ε = 9.263 μm, which is approximately half that of the predicted on-axis speckle size given above. In Fig. 6 we plot εs as a function of displacement from the optical axis over the range 0 ≤ x ≤ 16 cm for the square aperture case. The gap in the data points arises due to the discontinuity discussed in Subsection 4.A.

2. Circular Aperture Case (FST)
Substituting the ABCD values from Eq. (33) into Eq. (26), the speckle width is

εs = 1.22λx/D0.

(37)

The corresponding expression governing the on-axis longitudinal speckle size, Eq. (30), is

Δz/z = 8λ/D0,

(38)

and therefore εs is given by

εs = Δz = 8λ(x/D0)²,

(39)
in agreement with [13]. For an optical system with z = 20 cm, D0 = 10 cm, and λ = 633 nm, the speckle width at the output of the system is εs = 1.545 μm, while the on-axis longitudinal speckle size is εs = 20.256 μm. The equivalent on-axis longitudinal speckle size using the half-maximum definition is εs = 16.96 μm.

We now examine the change in longitudinal speckle size for speckles observed off-axis at r = ±2 cm in the output plane. For the FST case in Table 4, q = 4r/D0. Using this expression, the equations in Table 3 can be written as a function of p only and solved numerically. The p value resulting from Curve 1 is 3.801, which is within the specified range 0 ≤ p ≤ 4.563. Substituting this into p ≈ (D0²πΔz)/4λ(1/z²) from Table 2, the value of Δz at the point of decorrelation can be found. At r = 2 cm from the optical axis, off-axis longitudinal speckle size is εs = 12.254 μm. In Fig. 7 we plot εs as a function of displacement from the optical axis over the range 0 ≤ r ≤ 16 cm for this circular aperture case.

B. Single-Lens System
Using the matrix concatenation method described in Subsection 2.A, the ABCD parameters that describe the single-lens systems in Fig. 3(b) before and after displacement of the output plane are

ABCD1 = \[ \begin{bmatrix} 1 - z_2f & z_2 + z_1(1 - z_2f) \\ -1f & 1 - z_1f \end{bmatrix}, \]

(40a)

and

ABCD2 = \[ \begin{bmatrix} 1 - z_2 + \Delta z & z_2 + \Delta z + z_1(1 - z_2 + \Delta z) \\ -1f & 1 - z_1f \end{bmatrix}. \]

(40b)

In what follows, we assume z1z2 = z2(z2 + Δz) and fz2 = f(z2 + Δz).

1. Square Aperture Case
In this case the lateral speckle size is given by

εl = λ \[ z_2 + z_1 \left( 1 - \frac{z_2}{f} \right) \]

(41)

and on-axis longitudinal speckle size by

εs = Δz = 7.31λ \[ \frac{f(z_1 + z_2) - z_1z_2^2}{fL} \]².

(42)

The procedure for determining off-axis speckle size follows that used for the Fresnel system. Figure 6 plots longitudinal speckle size as a function of off-axis displacement x for the square aperture case when z1 = 8 cm, z2 = 12 cm, L = 10 cm, and λ = 633 nm.

2. Circular Aperture Case
For this case the lateral speckle size is given by

εl = \[ \frac{1.22λ}{D_0} \left[ z_2 + z_1 \left( 1 - \frac{z_2}{f} \right) \right] \]

(43)

and the on-axis longitudinal speckle size by
In Fig. 7, the longitudinal speckle size is plotted as a function of off-axis displacement \( r \) for the circular aperture case when \( z_1 = 8 \text{ cm} \), \( z_2 = 12 \text{ cm} \), \( D_0 = 10 \text{ cm} \), and \( \lambda = 633 \text{ nm} \).

6. CONCLUSION

The correlation properties of speckle fields at the output of paraxial optical systems with hard square and circular apertures at the input are examined using the mutual correlation coefficient of intensity. Formulating this correlation method using the linear canonical transform (LCT) allows us to derive general analytical formulas for lateral and on-axis longitudinal speckle size. A “boundary of correlation” (BOC) curve, defining the first minimum of the mutual correlation coefficient for all cases of longitudinal speckle was generated using a numerical search algorithm. Applying the resulting analytical fits to the various BOC curves, off-axis speckle size can be determined for such systems. Analytical fits to the half-maximum contour are also provided for the circular aperture case. The approach presented provides a general method for calculating speckle decorrelation and thus size in a practical way for a large class of paraxial optical systems.

The results of this paper are of particular significance to any application in which control over speckle size is desirable. The sensitivity and dynamic range of speckle metrology systems, for example, is highly influenced by speckle size. Also, with recent developments in nonimagining speckle photography configurations [3–5], speckle correlation characteristics in generalized optical systems are particularly topical.

Finally, we note that in the derivations presented in this paper, fully developed speckle is assumed, and the correlation extent of the field at the input plane is defined as sufficiently small that it can be adequately represented by a delta function [8]. It is, however, possible that these conditions are only approximately satisfied under certain experimental conditions. In such instances a more involved examination is required; see, for example, Section 4.5 [8]. Experimental verification remains necessary in order to fully assess the validity of the techniques presented. Such a study should indicate the suitability of the first minimum of the correlation coefficient of intensity as the most appropriate method of defining speckle size.

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