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<tr>
<th><strong>Title</strong></th>
<th>Spread-space spread-spectrum technique for secure multiplexing</th>
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<tr>
<td><strong>Authors(s)</strong></td>
<td>Hennelly, Bryan M.; Naughton, Thomas J.; McDonald, John B.; Sheridan, John T.; Gopinathan, Unnikrishnan; Kelly, Damien P.; Javidi, Bahram</td>
</tr>
<tr>
<td><strong>Publication date</strong></td>
<td>2007-05-01</td>
</tr>
<tr>
<td><strong>Publication information</strong></td>
<td>Optics Letters, 32 (9): 1060-1062</td>
</tr>
<tr>
<td><strong>Publisher</strong></td>
<td>Optical Society of America</td>
</tr>
<tr>
<td><strong>Link to online version</strong></td>
<td><a href="http://dx.doi.org/10.1364/OL.32.001060">http://dx.doi.org/10.1364/OL.32.001060</a></td>
</tr>
<tr>
<td><strong>Item record/more information</strong></td>
<td><a href="http://hdl.handle.net/10197/3420">http://hdl.handle.net/10197/3420</a></td>
</tr>
<tr>
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</tr>
<tr>
<td><strong>Publisher's version (DOI)</strong></td>
<td>10.1364/OL.32.001060</td>
</tr>
</tbody>
</table>
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A spread-space spread-spectrum technique for secure multiplexing

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WDF is four dimensional. Much of our analysis is limited to the 1D case, the extension to 2D being trivial. The WDF has many properties, only a few of which are critical in the present context. The first property is that of localization; in many practical problems it we assume that a signal is bounded within some finite region in the spatial and spatial frequency domains. The spatial extent, $W$, and frequency extent, $B$, are the minimum values such that

$$u(x) = 0, \quad |x| > W, \quad \int u(x)e^{-i\pi k_x x}dx = 0, \quad |k_x| > B.$$  

(2)

The second property relates to Parseval's theorem; the total energy of the signal, $E$, is

$$E = \int \phi(u(x))(x,k_x)dxdk_x.$$  

(3)

Applying Eqs. (2) and (3), the average energy density of the signal in phase space is given by $E/WB$. The third property of interest is the product theorem of the WDF. When two signals are multiplied in space, their WDFs are convolved along the $k_x$ axis:

$$\phi(u(x)v(x))(x,k_x) = \int \phi(u(x))(x,k_x-k')\phi(v(x))(x,k_x)dk'.$$

(4)

From Eqs. (2) and (4), the signal $u(x)h(x)$ will have a spatial width equal to the overlapping spatial distributions of the individual signals. Furthermore, the resulting spatial frequency distribution will have a bandwidth equal to the sum of the bandwidths of the product signals, $B_u + B_h$. The final property of interest is the relationship of the WDF to the Fourier transform (FT). If a FT is applied to a signal, the corresponding WDF rotates by $\pi/2$ rad: $\phi(u(x))(x,k_x) \rightarrow \phi(u(x))(-k_x,x)$. In the case of an FT with focal length $f$ and wavelength $\lambda$, we have the following relationship: $\phi(u(x))(x,k_x) \rightarrow \phi(u(x))(-\sqrt{f/k_x},x/\sqrt{\lambda})$. If Eq. (2) holds, then the output OPT bandwidth is $B/\sqrt{f}$; i.e., the OPT does not simply rotate the WDF but also stretches it.

Turning to the DRPE system, and with the aid of Fig. 1 and Table 1, we describe the evolution of a signal's spatial and spatial frequency distributions as it propagates through the system. The input signal has the Wigner volume chart shown in Fig. 1(i), where the signal is depicted having a width and bandwidth as defined in Table 1. The average energy density can be calculated at any plane as $E/(\text{Width } x)$ (Width $k_x$). If our image signal has been coded for efficient storage, then it will seem random in nature, and we may assume that it fully occupies the volume shown in Fig. 1(i). D1 and D2 are assumed to be lossless and are designed to have the well-specified widths and bandwidths listed in Table 1. When the signal passes through D1, the product signal has an increased bandwidth, but the total energy must remain the same. Therefore the average energy density is reduced by a factor proportional to the spread. The resulting Wigner volume chart is shown in Fig. 1(ii), and the relevant values are given in Table 1. The first FT rotates the chart by $\pi/2$ rad, see Fig. 1(iii), and the resultant signal passes through D2. The spatial frequency domain is again stretched (we note that this is actually the spatial domain of the input signal), and, since the total energy again remains the same, the average energy density in phase space is further reduced; see Fig. 1(iv). The final FT rotates the chart once again as shown in Fig. 1(v). This 1D signal, with known extents in $x$ and $k_x$, is now captured. We see that it is important to match $W_{IN}$ and $W_{D1_x}$ and also $\sqrt{f}(B_{IN}+B_{D1})$ and $W_{D1_x}$. Correct decryption of the signal follows a very similar pattern, in the exact reverse. Figures 1(ii)–1(v) in reverse order describe the evolution of a correctly decrypted signal. D2 now acts to despread the signal in the space domain, while D1* is not needed, since despreading in the frequency domain does not affect the intensity of a decrypted signal.

Multiplexing is implemented by using a standard DRPE encryption system with different keys for each input image. Our demultiplexing system is shown in Fig. 2, made up of a standard DRPE decryption system except that we also use D1* to despread in $k_x$. We also apply apertures in the decryption plane and its Fourier plane to remove all the energy of incorrectly decrypted signals except that part that lies inside the low-pass regions in the four dimensions. Figures 1(i)–1(v) in reverse describe the total evolution of demultiplexing. When decryption is performed by using an incorrect set of diffusers, the signal will not be de-
energy density at any plane is given by $ky$ and $kx$, and are used to despread and decrypt. If $N$ requires knowledge of both the phase keys and filters robust than the traditional DPRE, since decryption

can be determined. Taking the latter value and the dynamic range of the input signals into account, one may determine the sufficient parameters for the diffusers ($B_\text{D1}$ and $B_\text{D2}$) such that each image may be recovered with minimal error. We also note that a further limit is imposed on the number of images by the dynamic range of the recording medium. We believe that this limit may also be represented efficiently by using Wigner analysis, but that is beyond the scope of this Letter.

In Fig. 3 we show the results of a simulation to multiplex and demultiplex three 128 $\times$ 128 binary images. This case is clearly not optimal, since the input images have not been coded to evenly distribute the energy in the frequency domain. We chose $B_\text{IN} = B_\text{D1}$, $W_\text{IN} = \sqrt{\rho} B_\text{D2}$, $B_\text{IN} = B_\text{D1}$, $W_\text{IN} = \sqrt{\rho} B_\text{D2}$, so that the encrypted image had twice the width and bandwidth of the input, and therefore an incorrectly decrypted image had three times the width and bandwidth of the input. Thresholding was not applied to the results shown in Fig. 3. After thresholding the bit error rate for this case is less than 1%. The performance of the technique is currently being investigated for large numbers of inputs and different spreads. We acknowledge that a practical implementation will differ from the ideal simulation, and we are also pursuing experimental validation. Similar analyses may be applied to optimize the performance of architectures outlined in Refs. 6–14.

We acknowledge the support of the Irish Research Council for Science Engineering and Technology. B. Hennelly's e-mail address is bryanh@cs.nuim.ie.

References